

Steering Behaviors




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UCSC CMPM146 Game AI

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In this talk

- History (mine and steering behaviors)
 - Flocking boids (self-organization, emergence)
 - Generalizing steering behaviors
 - OpenSteer (open source library)
 - Other collective behavior models (stigmergy)
 - Learning/optimization applied to steering behaviors
- 
- history
versus
talk order

History

- Childhood interest in bird flocks and “model worlds”
 - College work on multi-agent simulations in 3d worlds
 - SIGGRAPH 1986: first boids motion tests
 - SIGGRAPH 1987: boids paper, *Breaking the Ice*
 - GDC 1999: paper on generalized steering behaviors
 - GDC 2000: real time interactive boids
 - 2003 OpenSteer (C++ lib, ports to other languages)
 - 2006: high performance multicore/GPU versions
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What are steering behaviors?

- Help autonomous characters navigate their world
 - Get from here to there, without bumping into things
 - Important in modeling *embodied* multi-agent systems
 - Simulation model of human crowds and animal groups
 - Applications in games, VR, and films (crowd scenes)
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Steering behaviors: assumptions

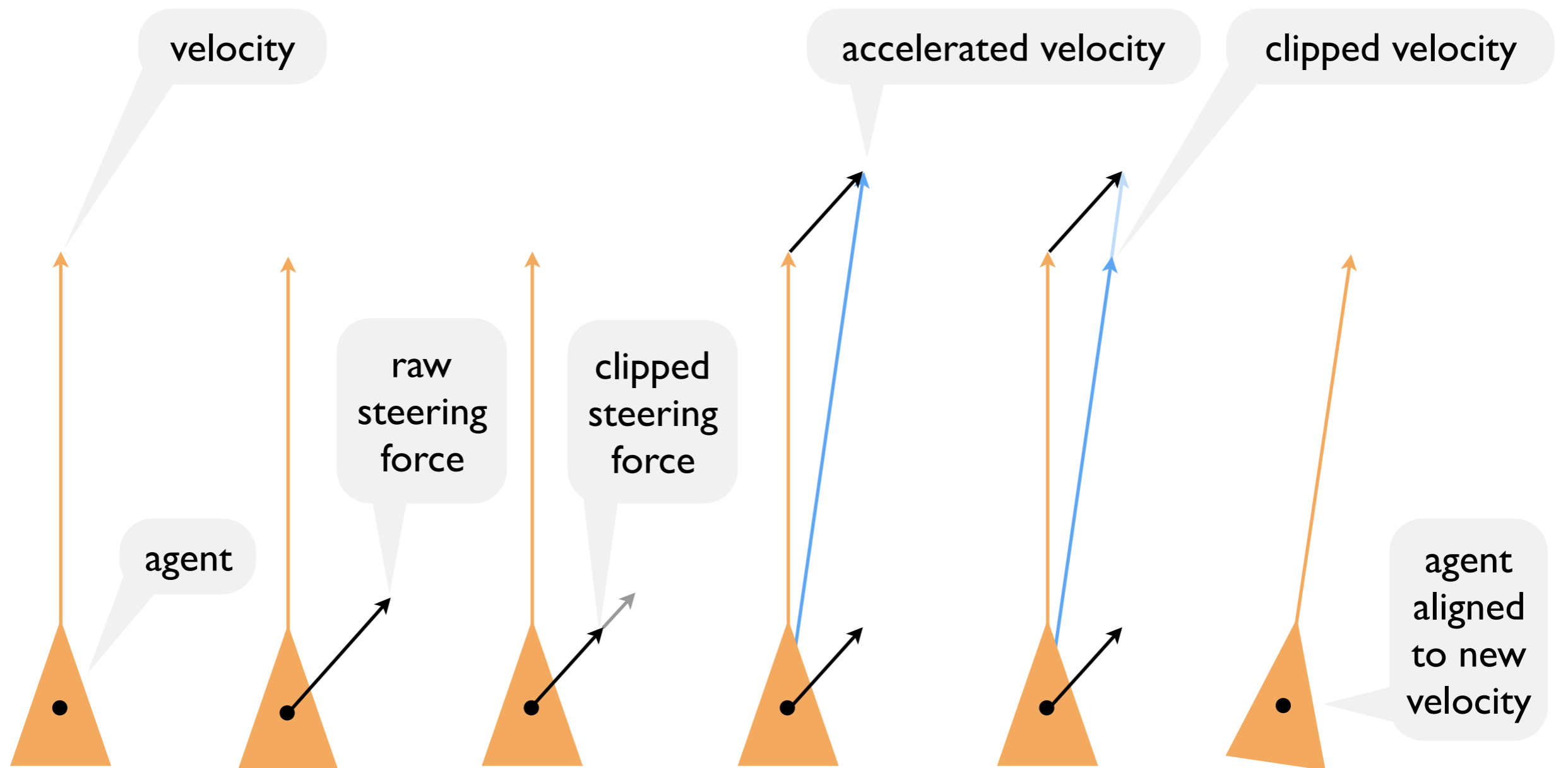
- Position and orientation have continuous values
 - Speed high enough that momentum matters
 - Each agent runs their own behaviors
 - Behaviors based on perception of local environment
 - Environment is world geometry plus nearby agents
 - Typically reactive behavior, not long term planning
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Typical steering behaviors

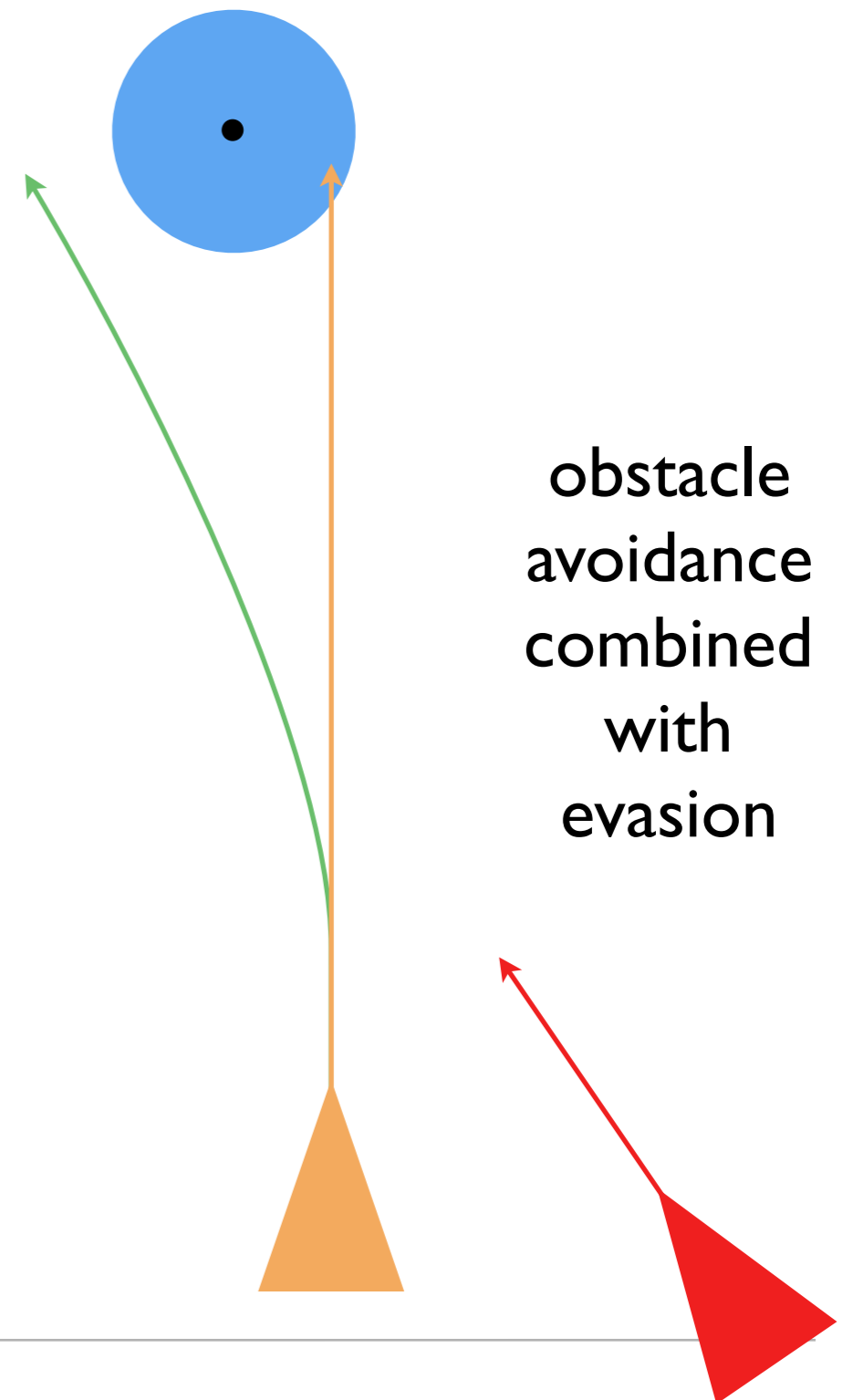
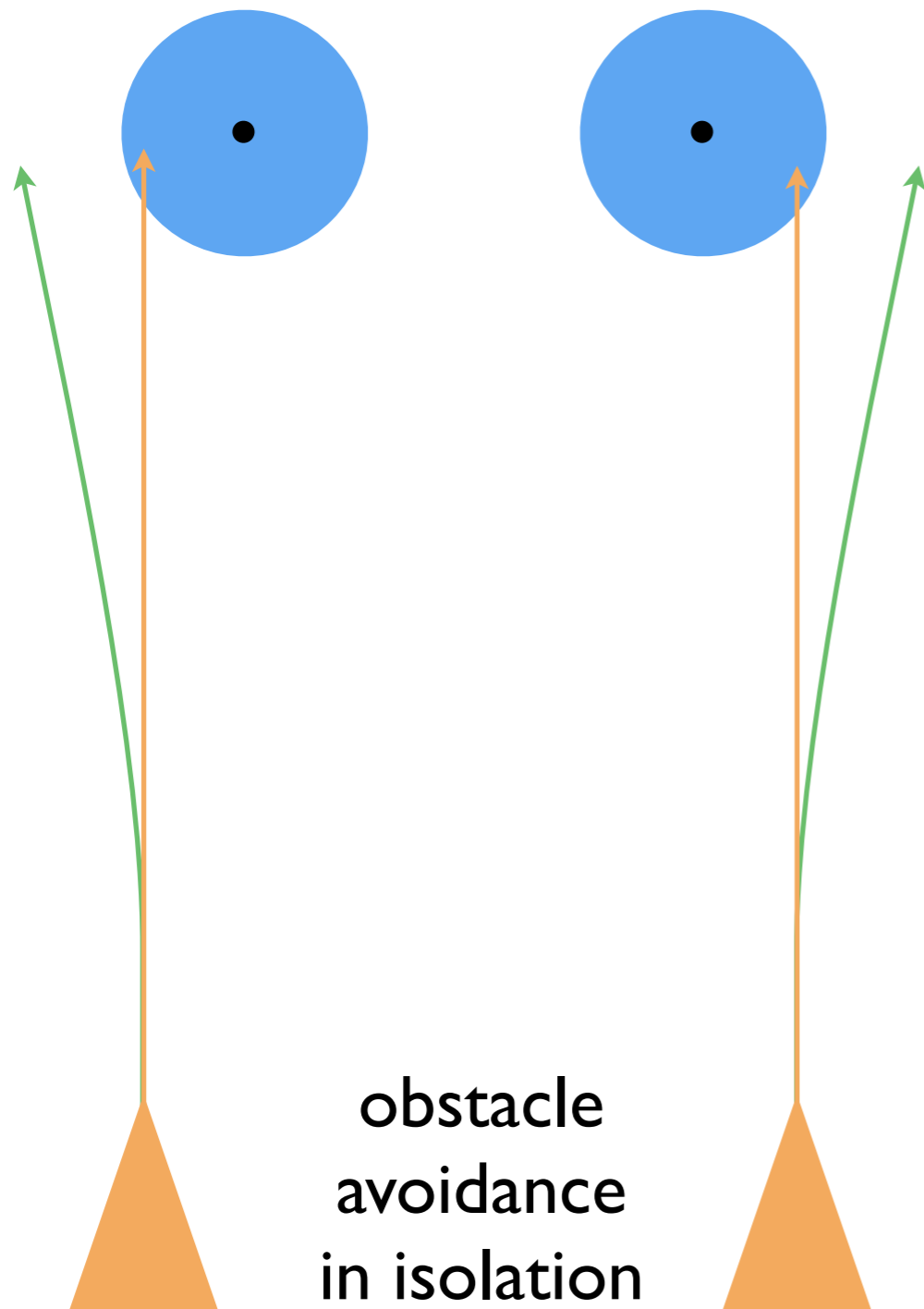
- seek / flee
 - pursue / evade
 - wander
 - arrival
 - avoid obstacle
 - containment
 - path following
 - wall following
 - flow field following
 - flocking
 - separation
 - alignment
 - cohesion
-

Steering Behaviors

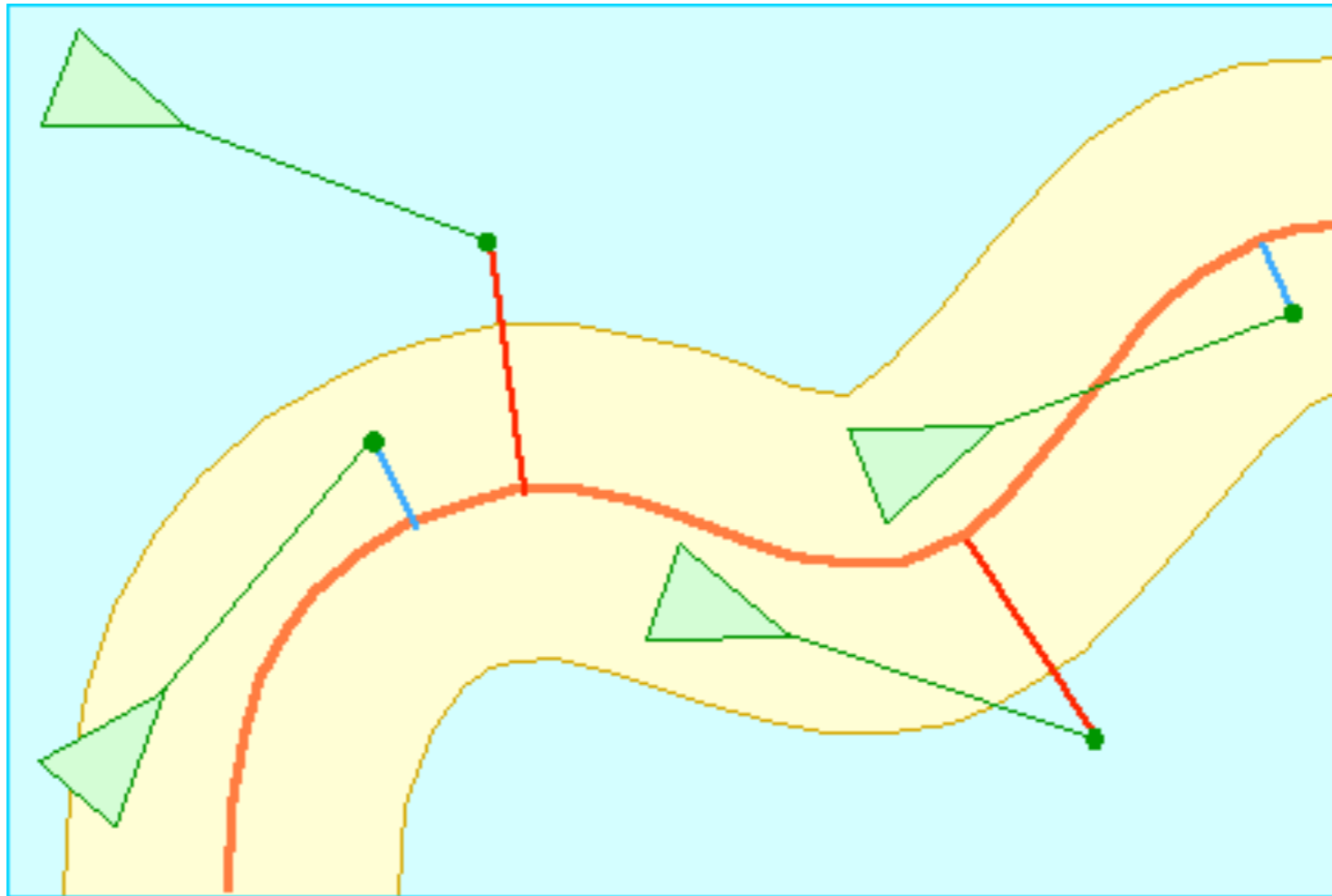
applying steering forces to velocity-aligned point mass “vehicles”

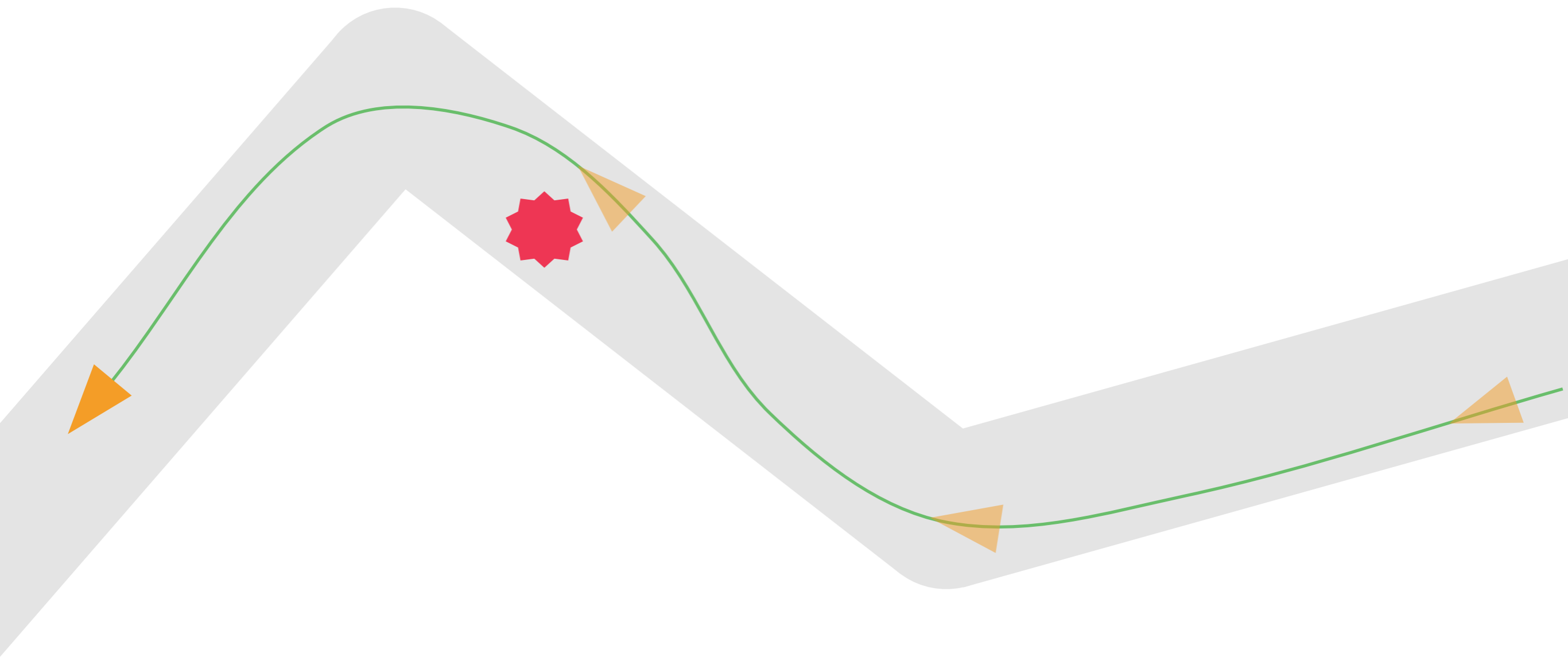


Combining steering behaviors

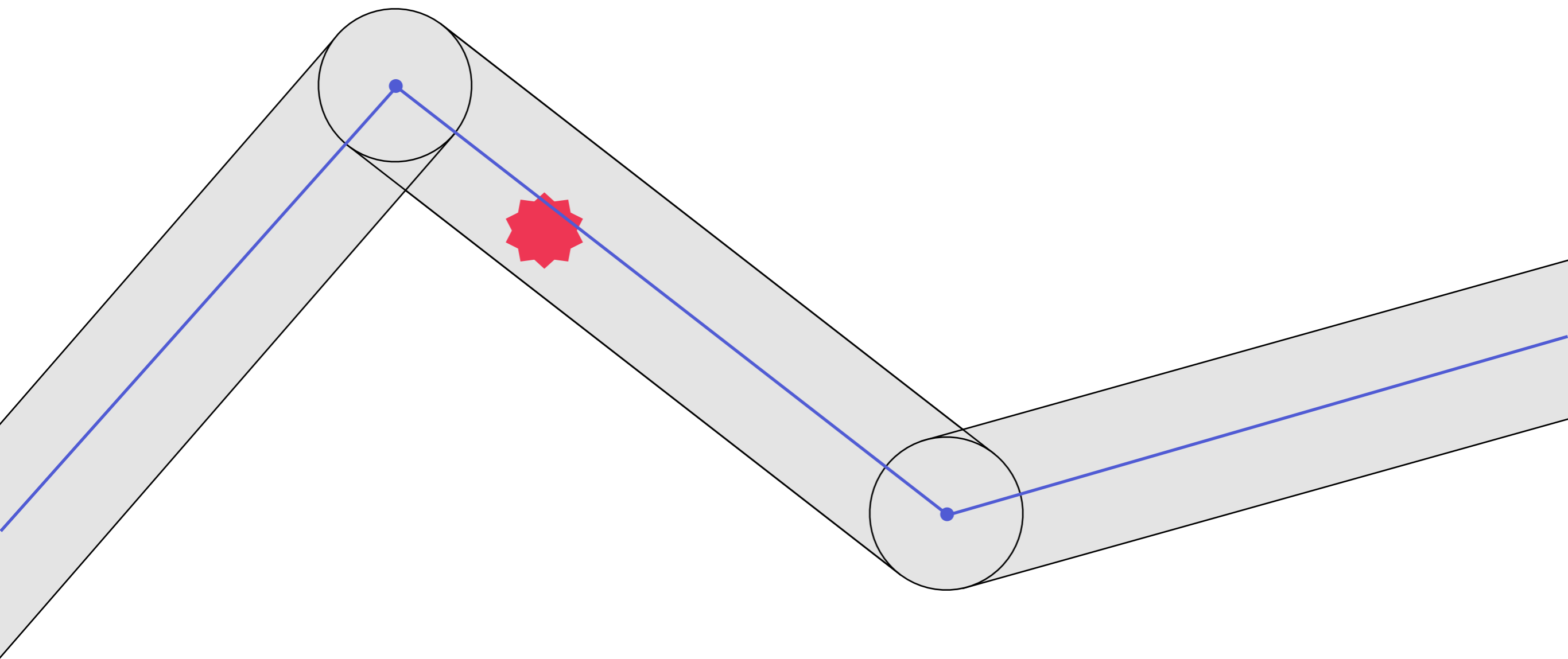


Steering behavior example: path following

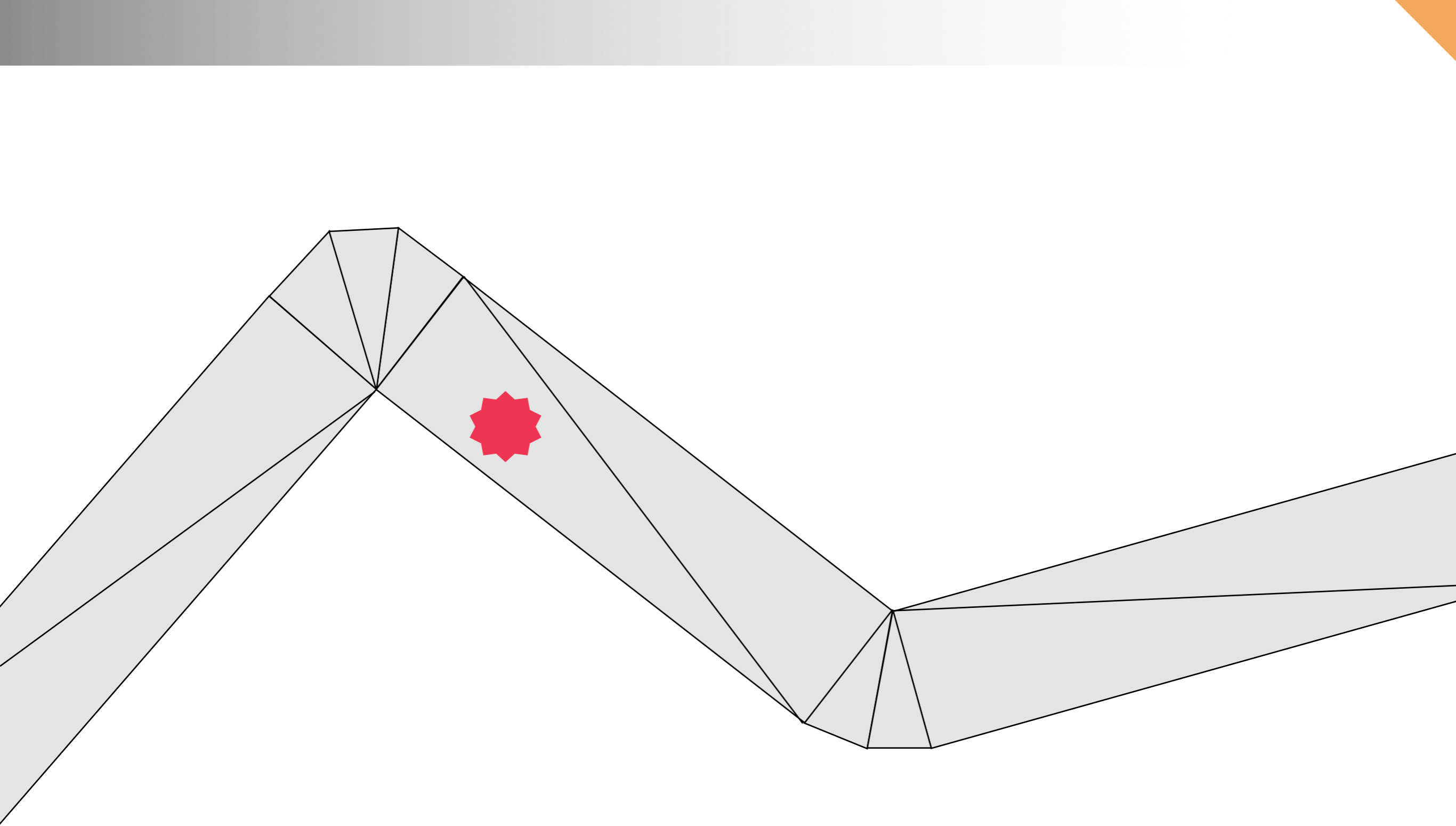




composed steering behaviors:
follow path and avoid obstacle

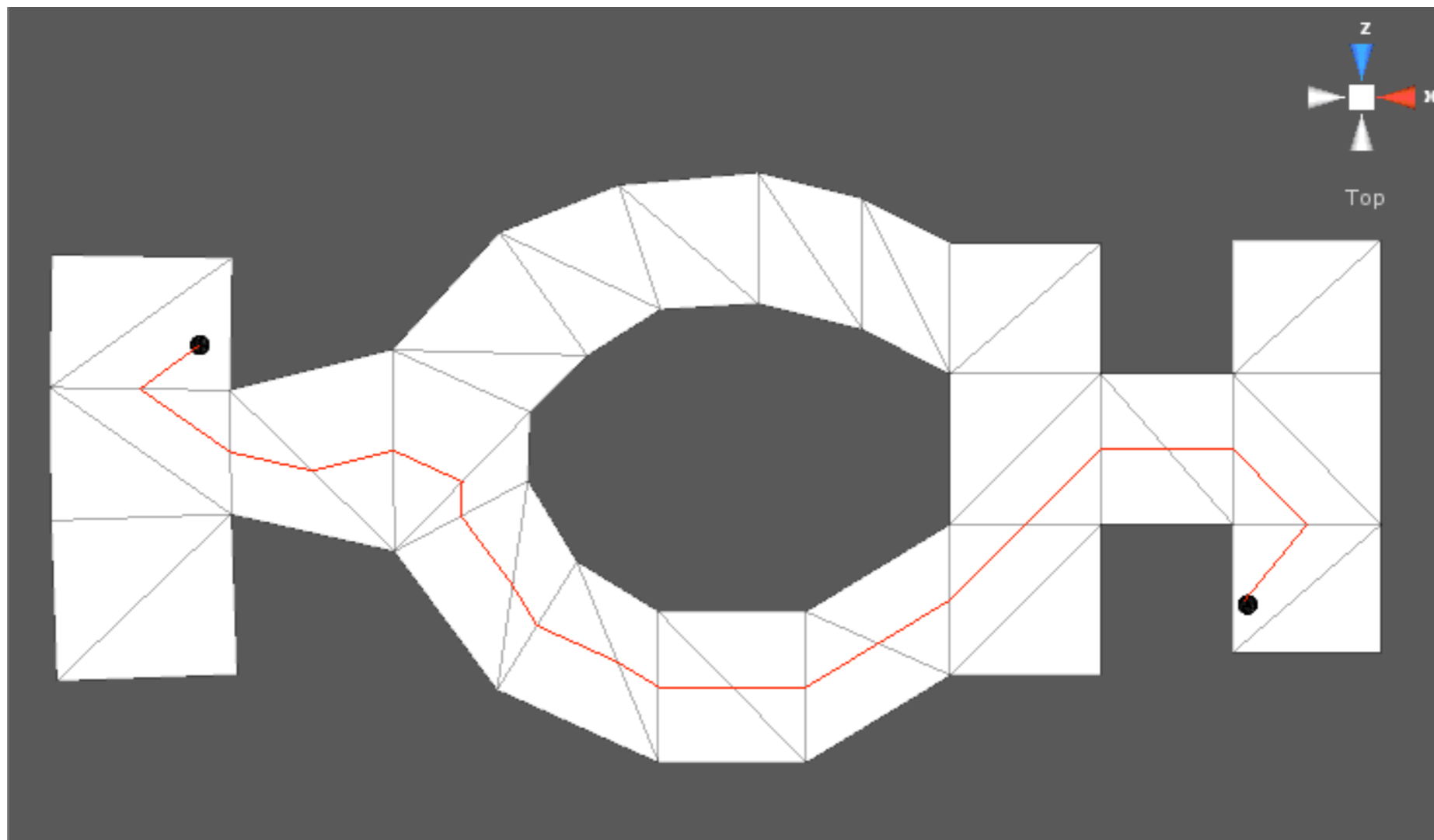


sphere swept along polyline



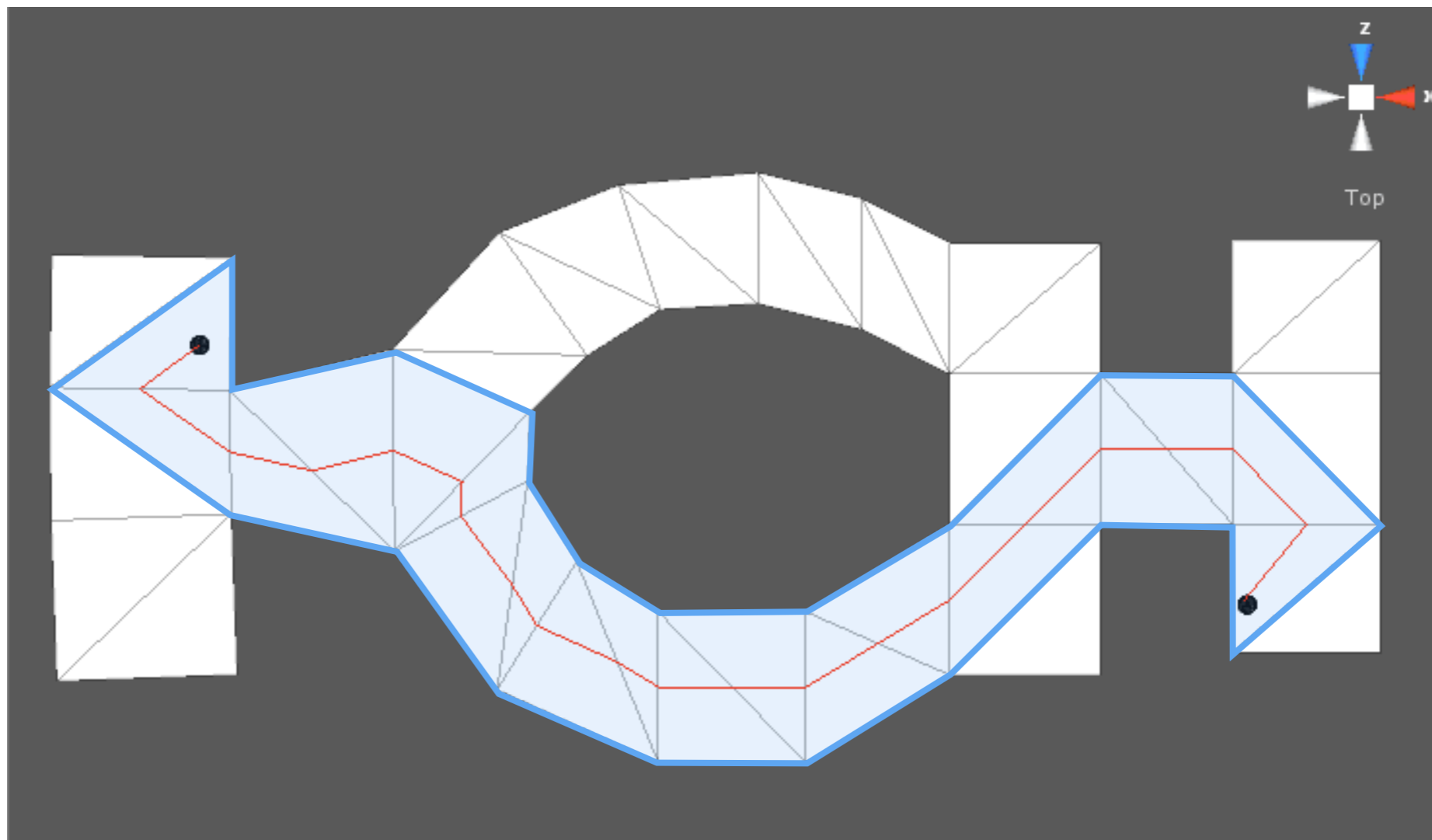
navigation mesh

navmesh: a parenthetical aside



Michael Grenier (2011) <http://mgrenier.me/2011/04/pathfinding-102-ish/>

navmesh: a parenthetical aside

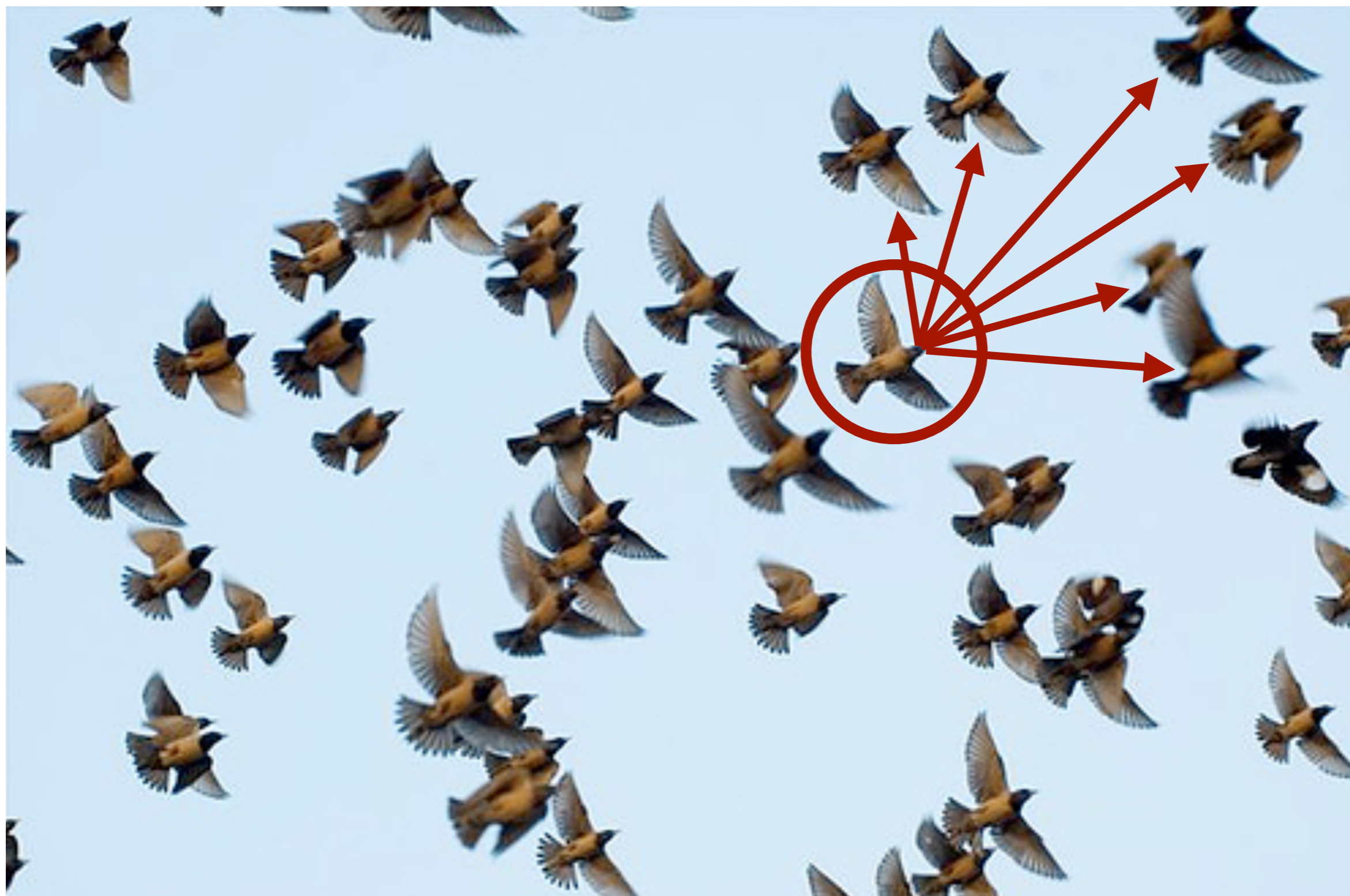


Michael Grenier (2011) <http://mgrenier.me/2011/04/pathfinding-102-ish/>

Boids



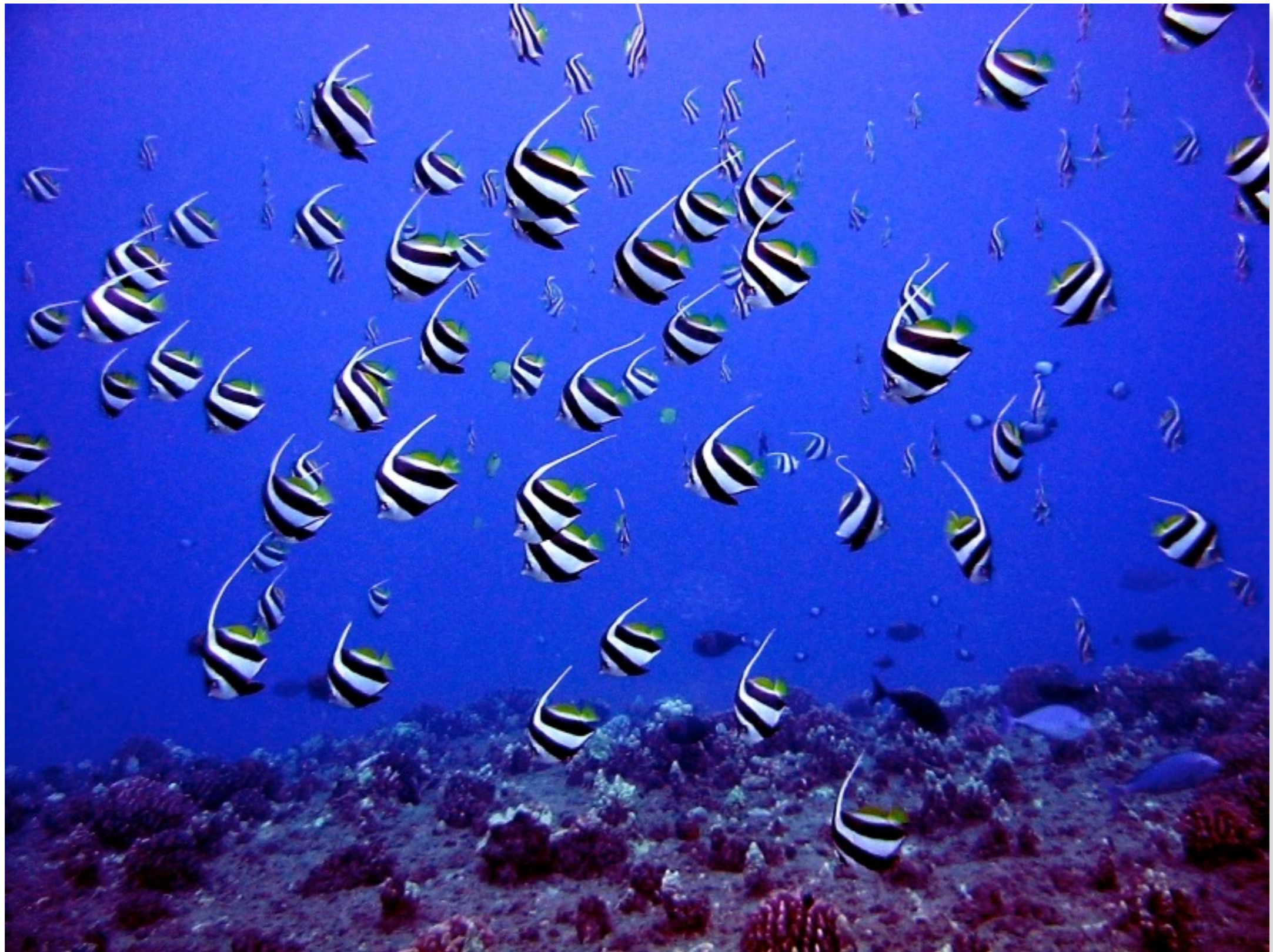






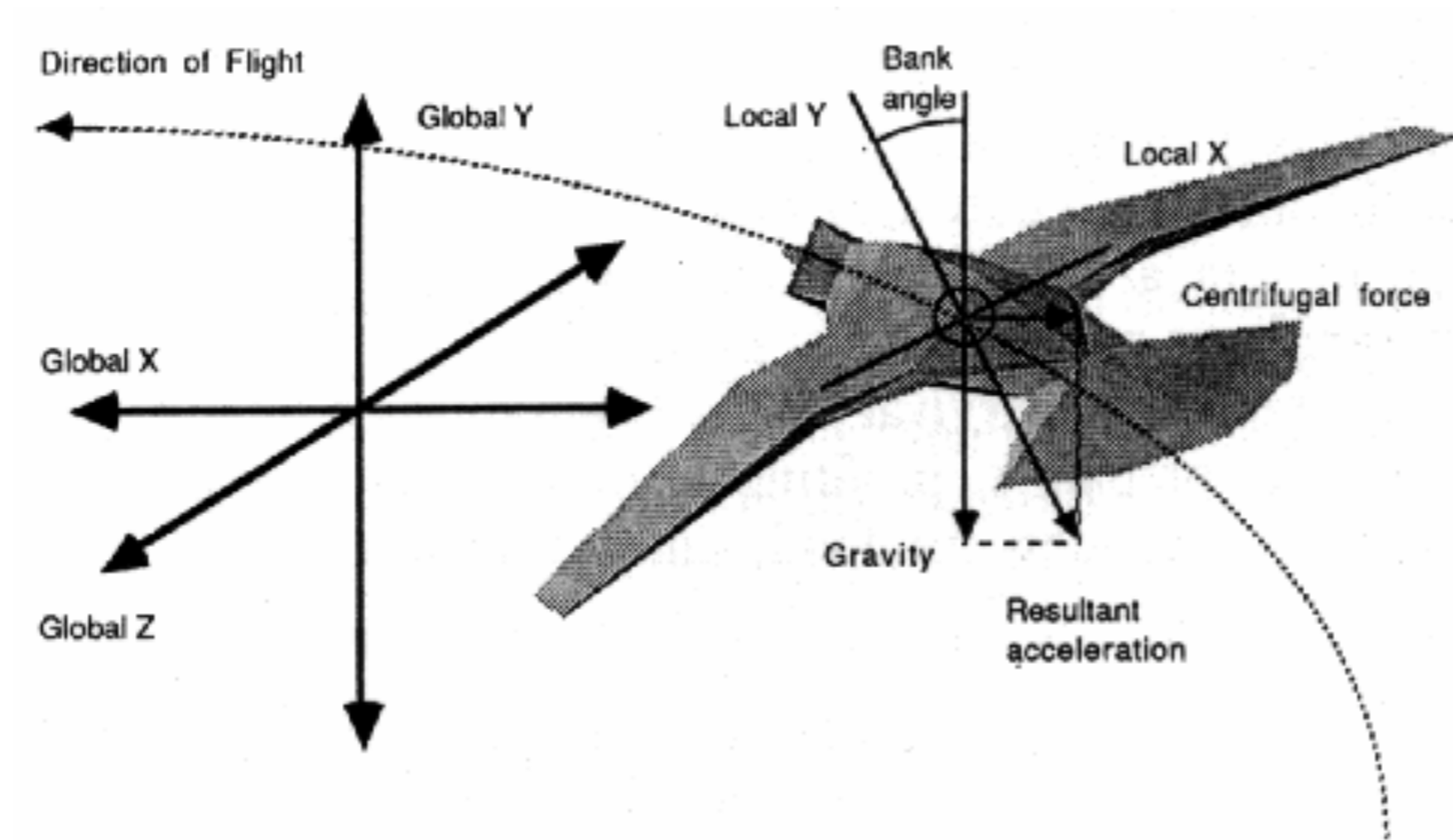






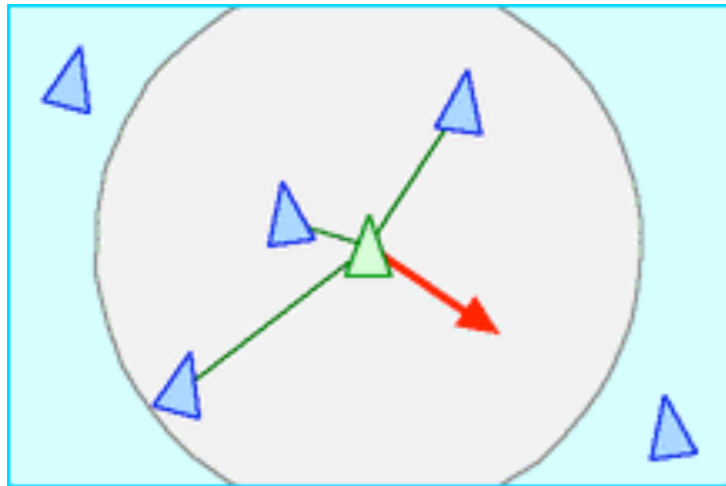
Self-organization

- many autonomous agents (“multi-agent simulation”)
 - local interaction between neighboring agents
 - emergence of global behavior or structure
-

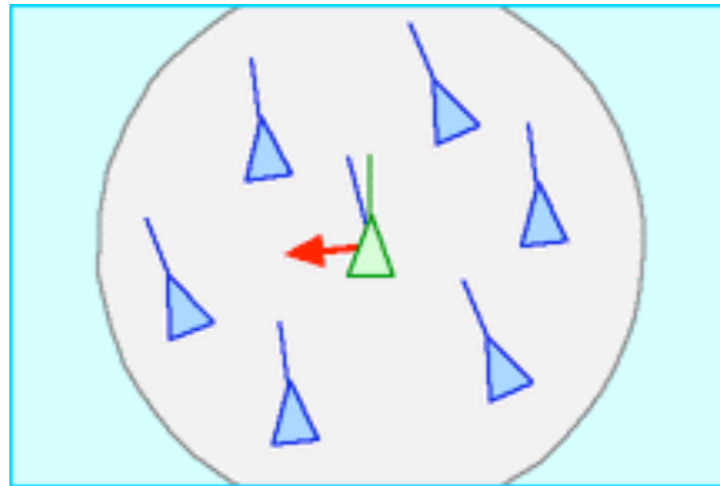


bird's local coordinate system and *banking*

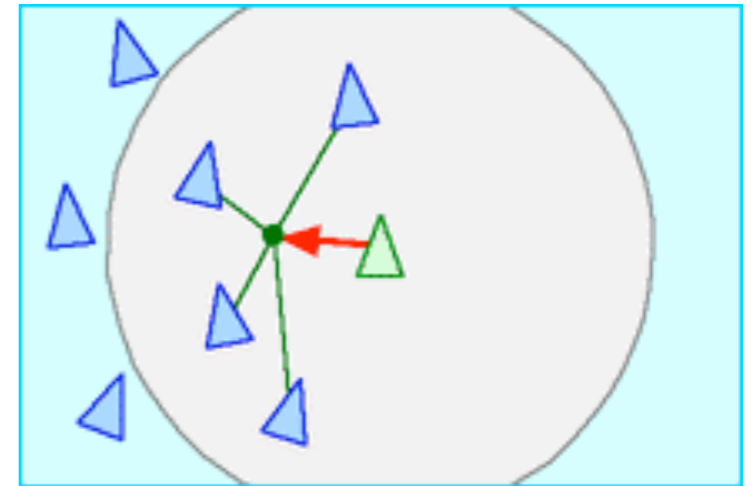
Three component steering behaviors of flocking:



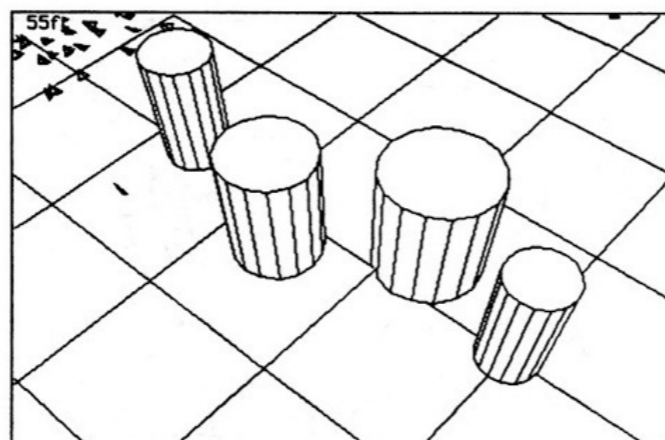
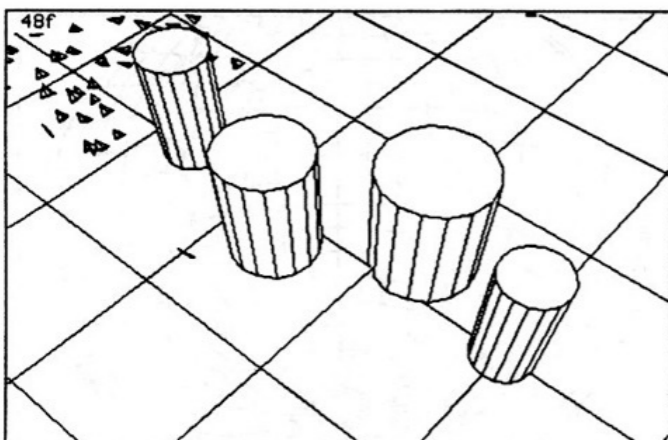
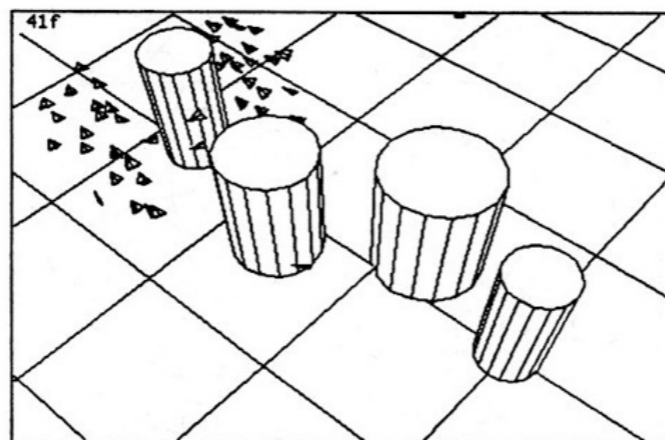
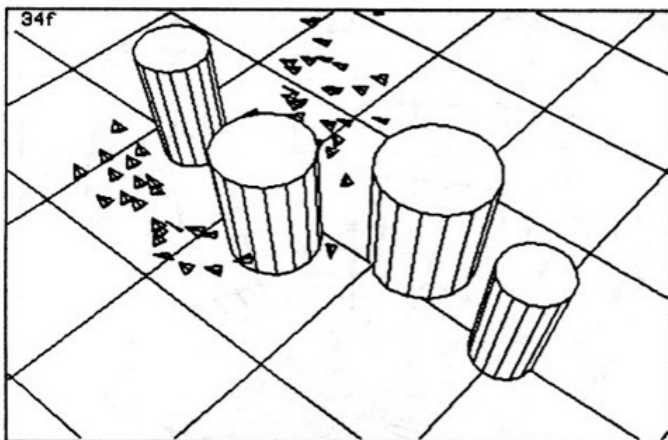
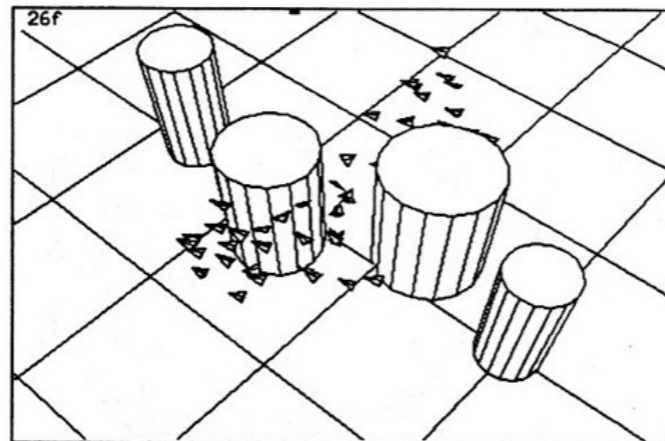
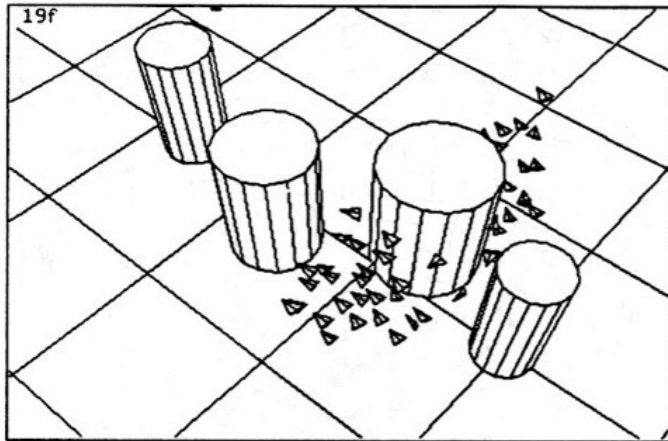
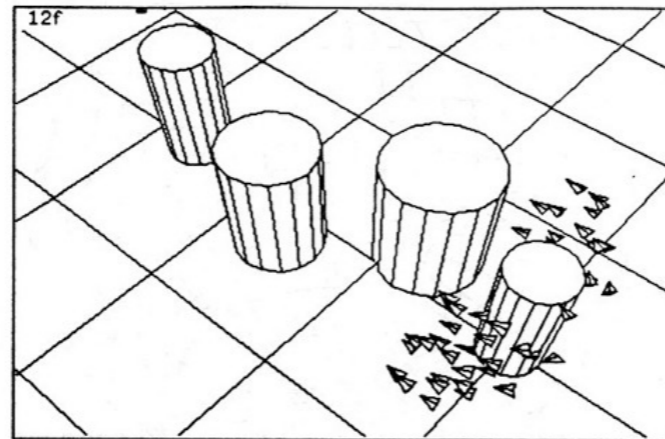
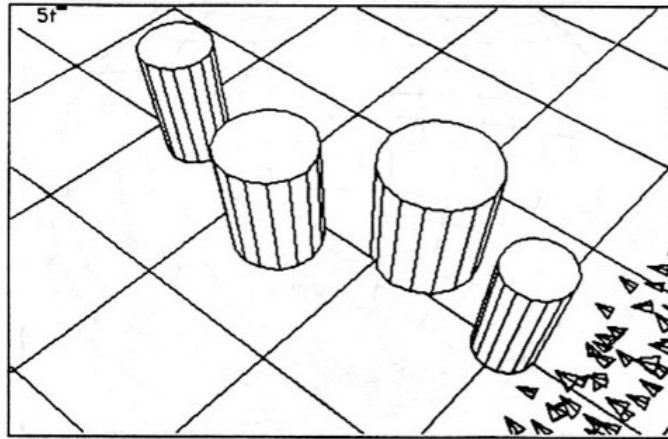
Separation



Alignment



Cohesion



Early boids motion test:

- flocking
- separation
- alignment
- cohesion
- seek
- obstacle avoidance

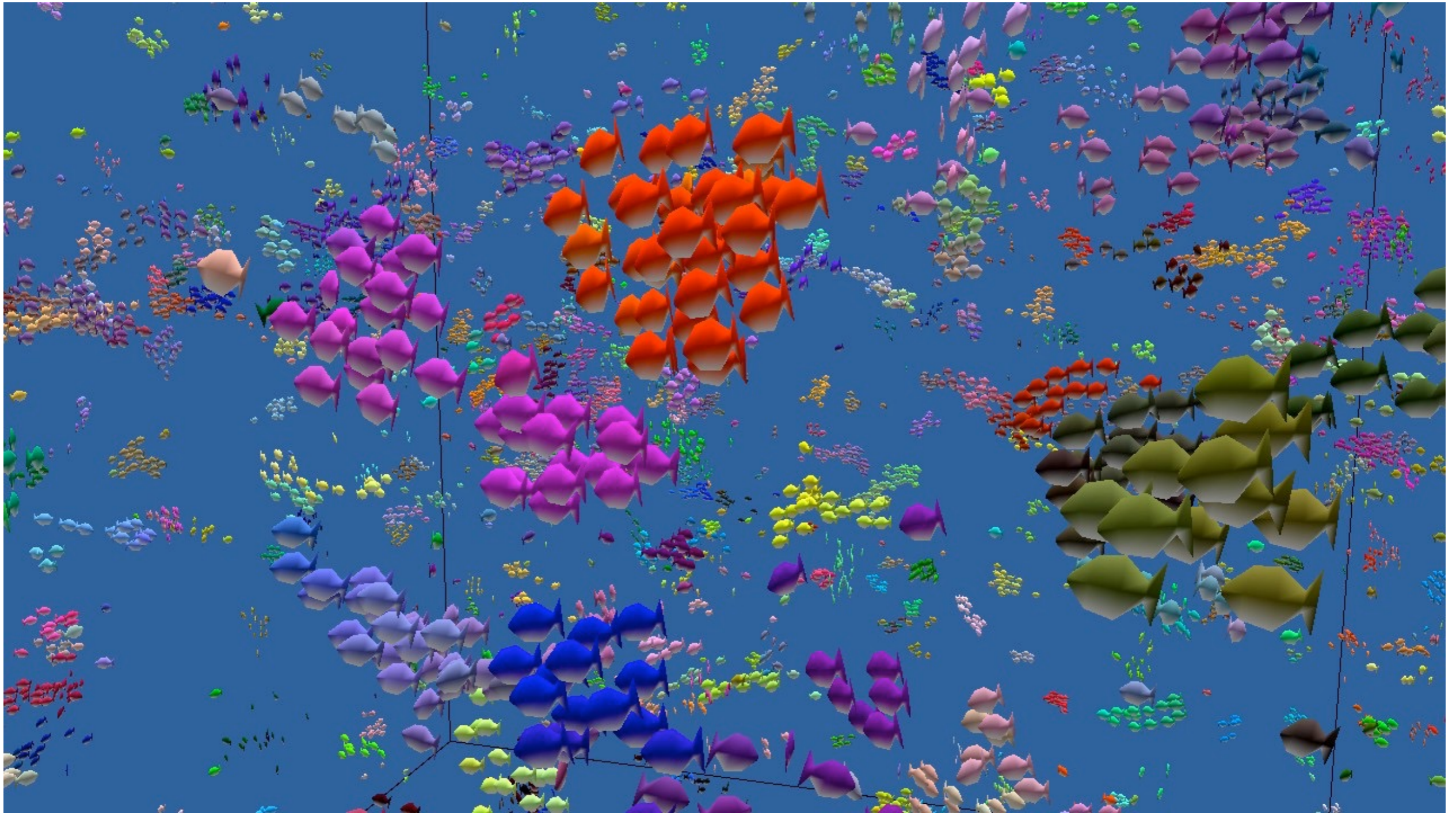
1986 screen grabs from
Symbolics Lisp Machine



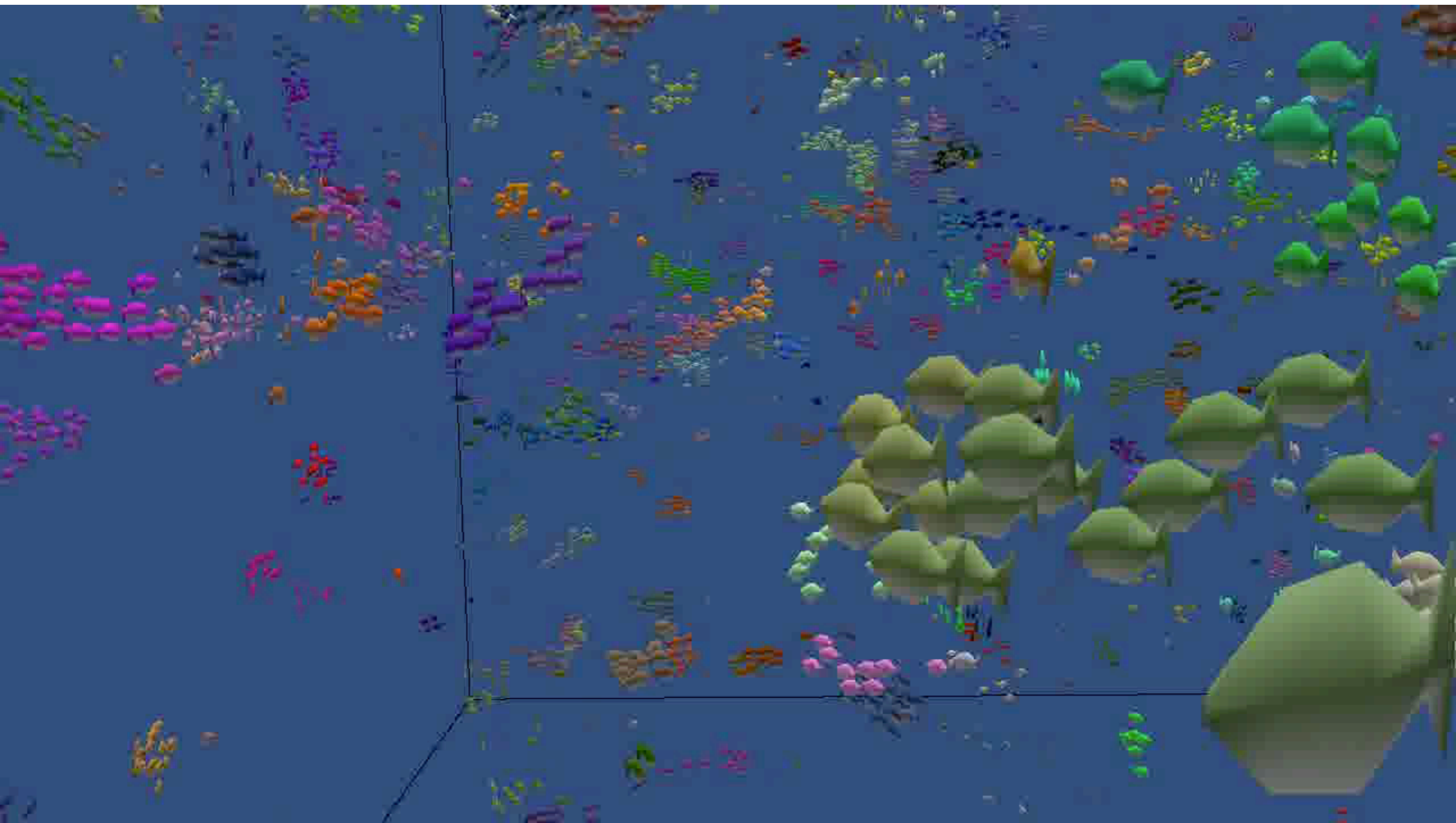
(Stanley and Stella in) Breaking the Ice
1987

SYMBOLICS

GRAPHICS DIVISION



Real time boids on PS3 — about 10,000 at 60Hz — PSCrowd, 2006



[chameleon test on youtube](#)

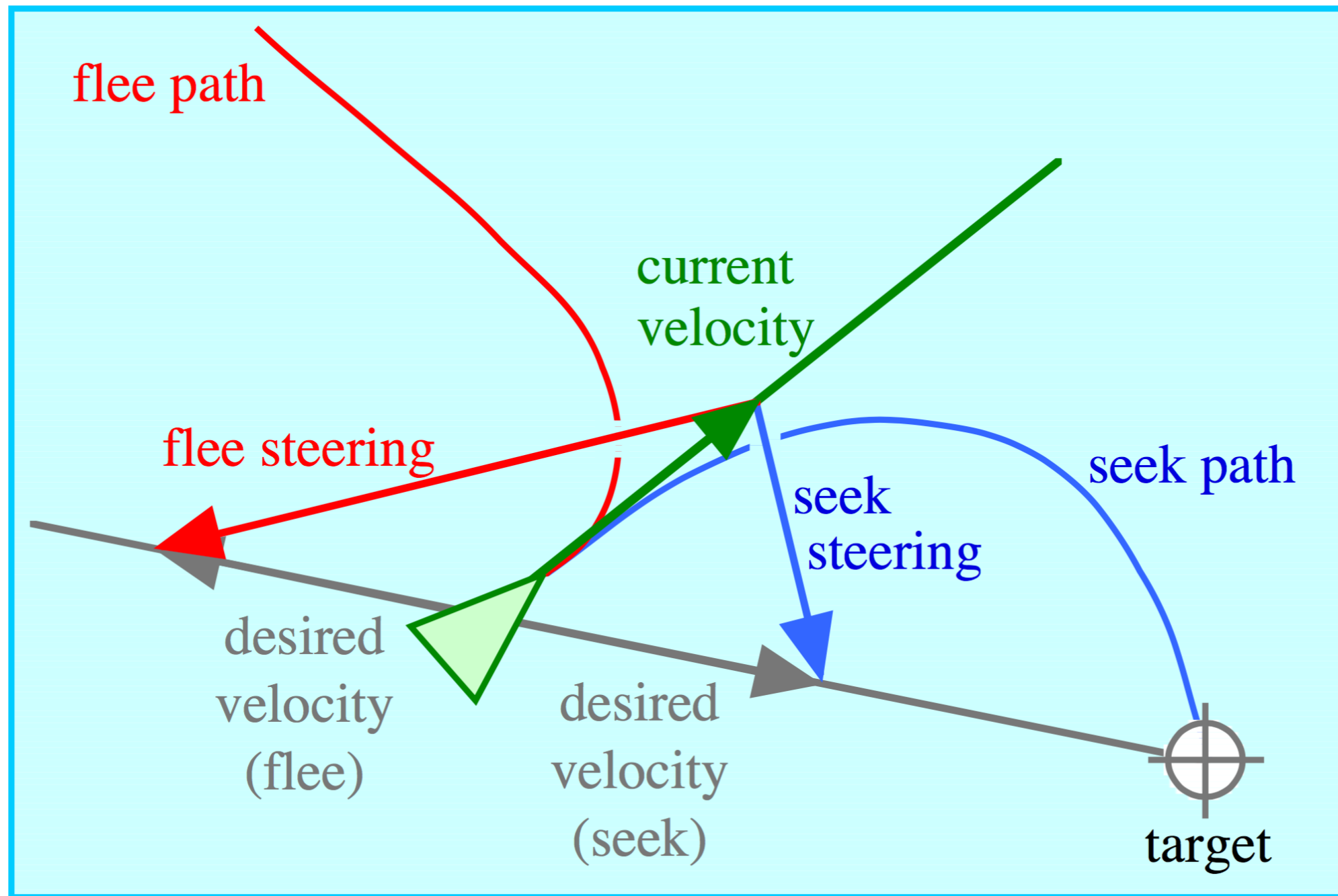


[final 12k fish on youtube](#)

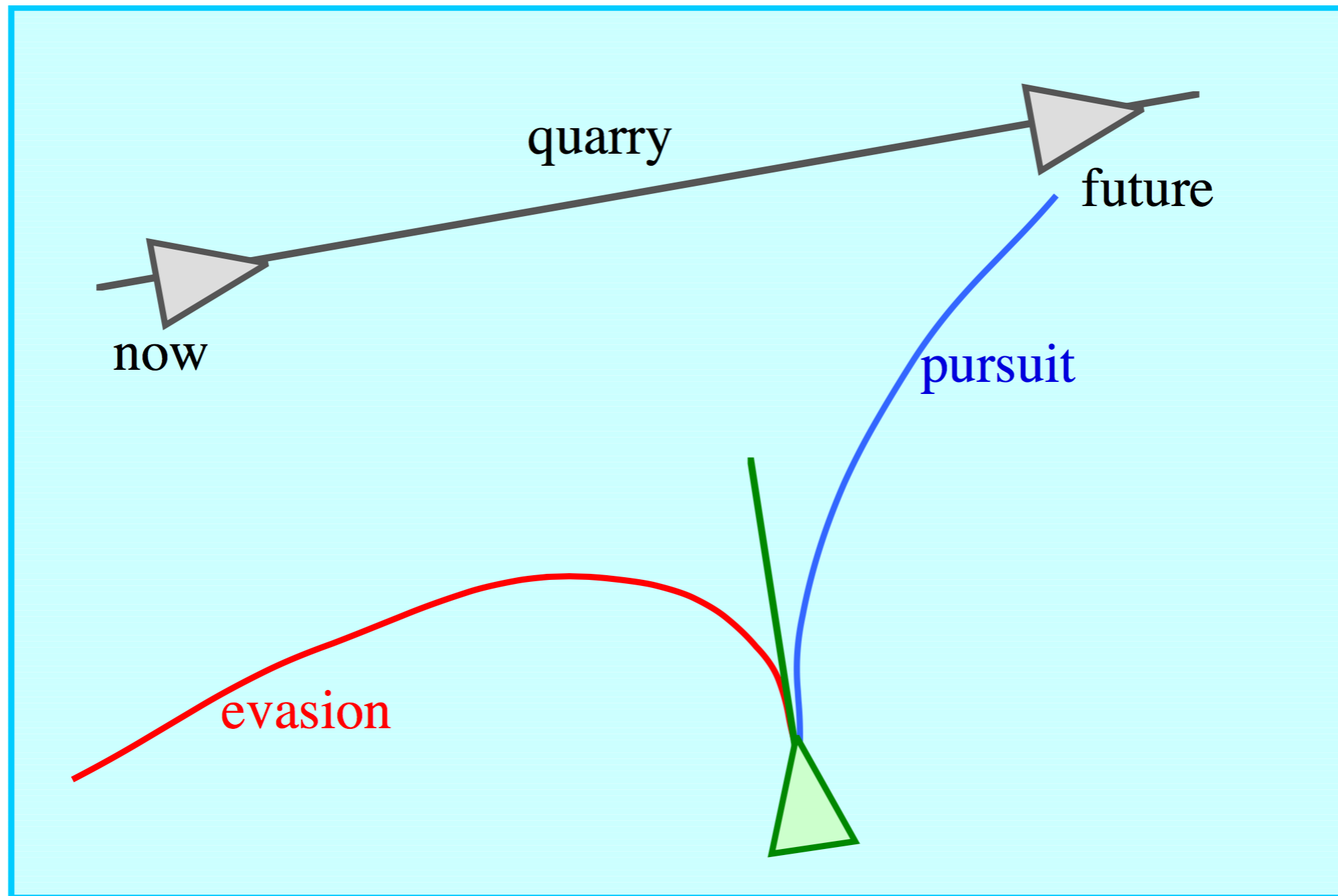
Steering Behaviors

Steering behaviors

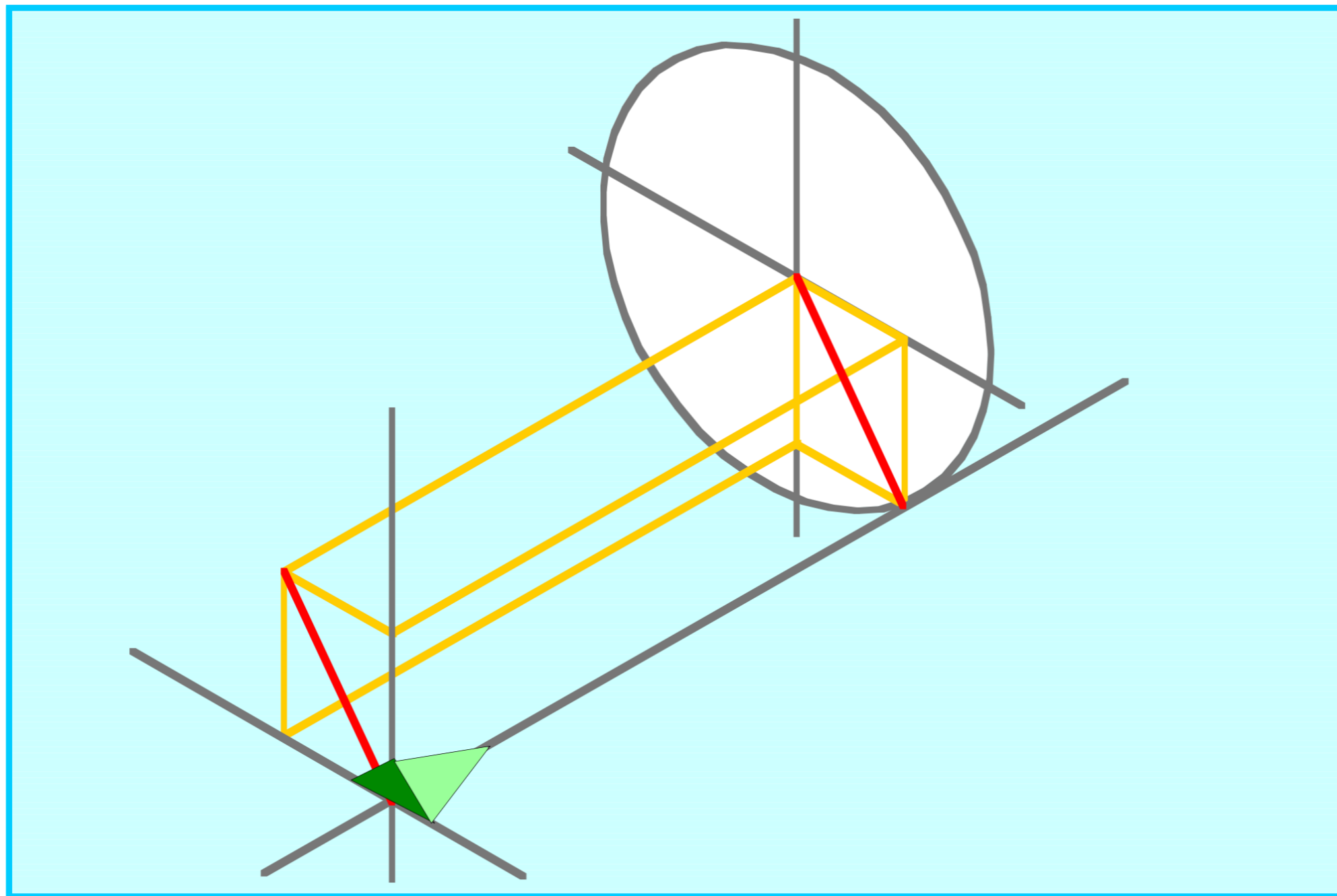
- Generalization of the three components of boids
 - Toolkit of behaviors for autonomous characters
 - Goal-oriented motion controllers
 - To model animals, humans or vehicles
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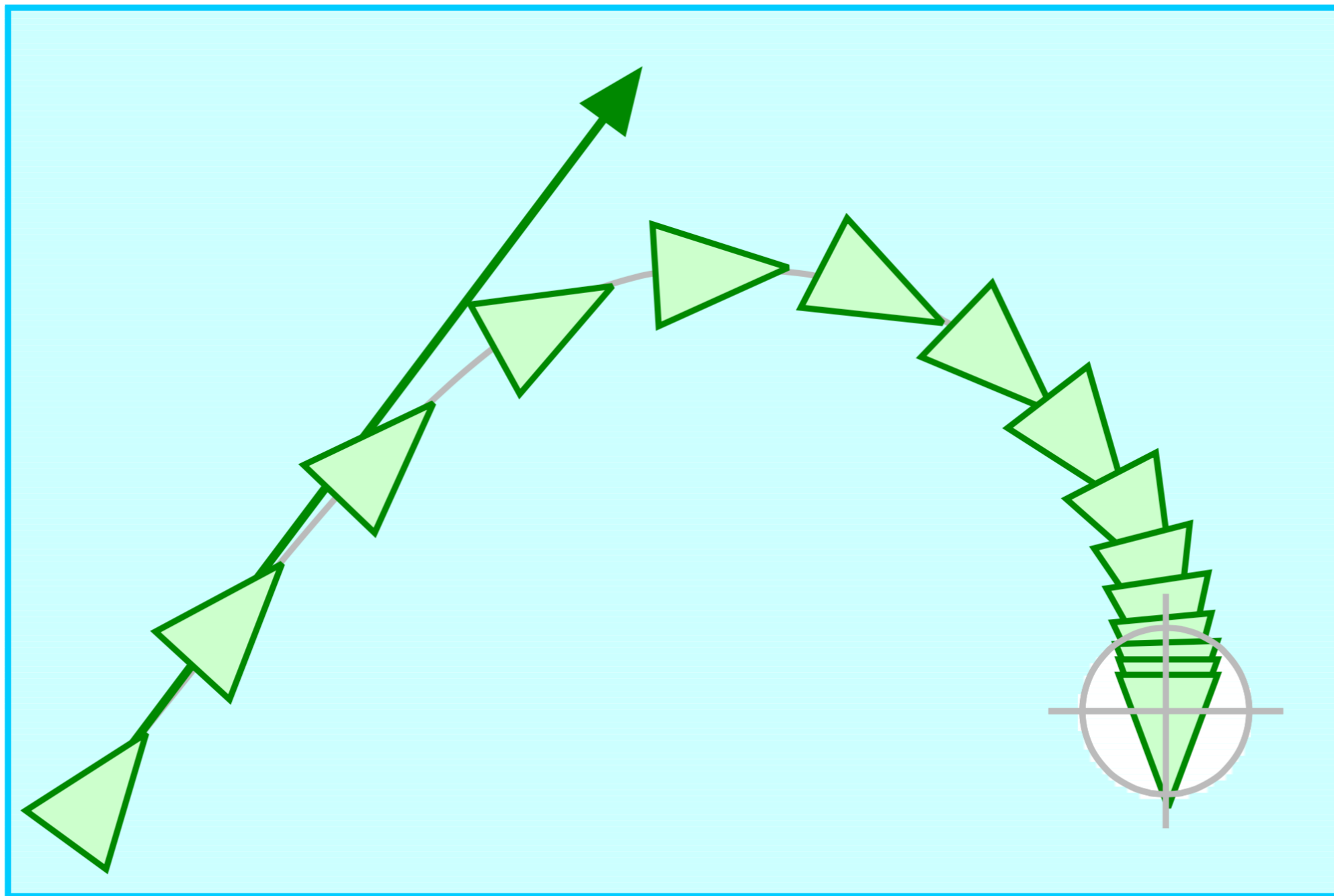
seek and flee steering behaviors



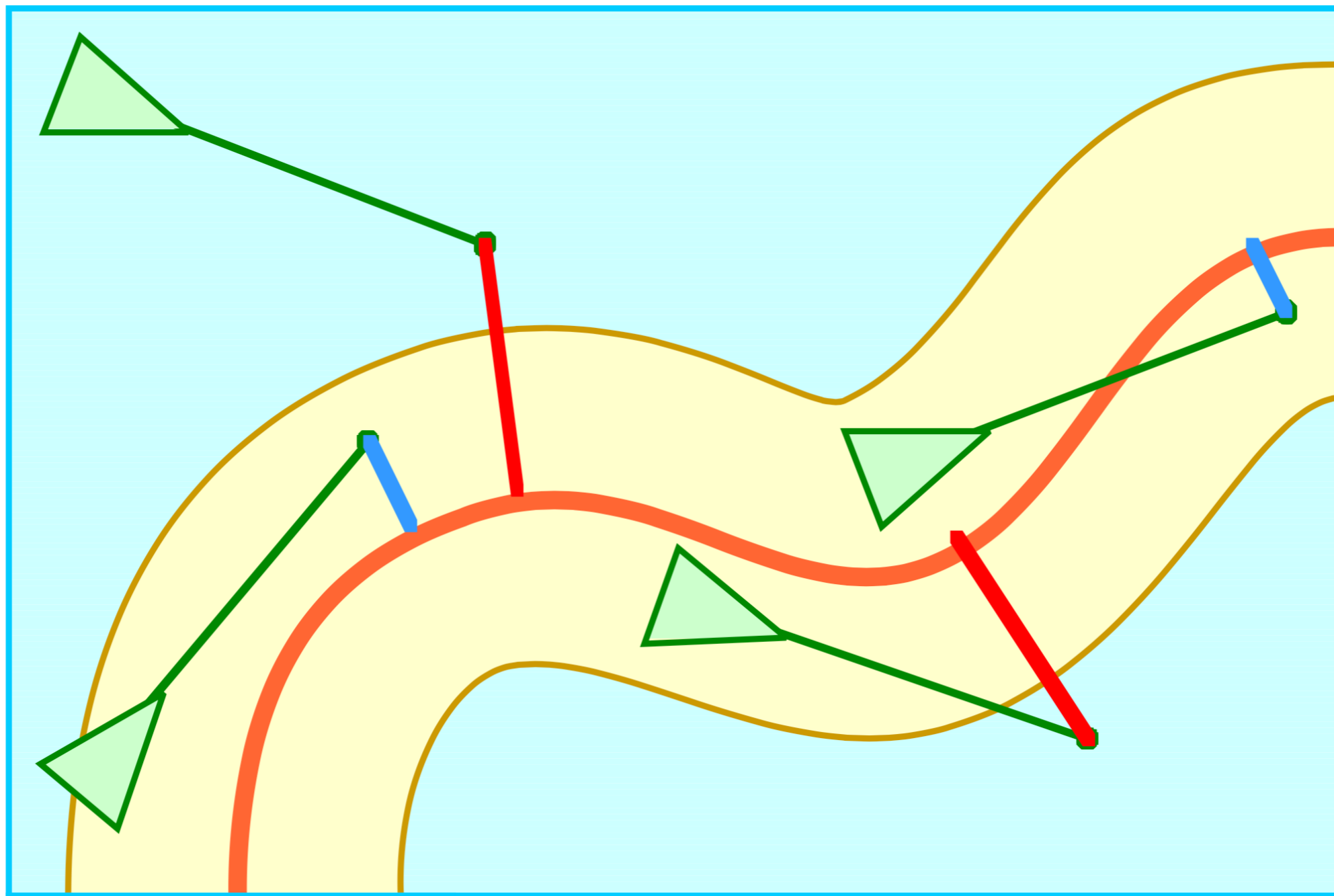
pursuit and evasion



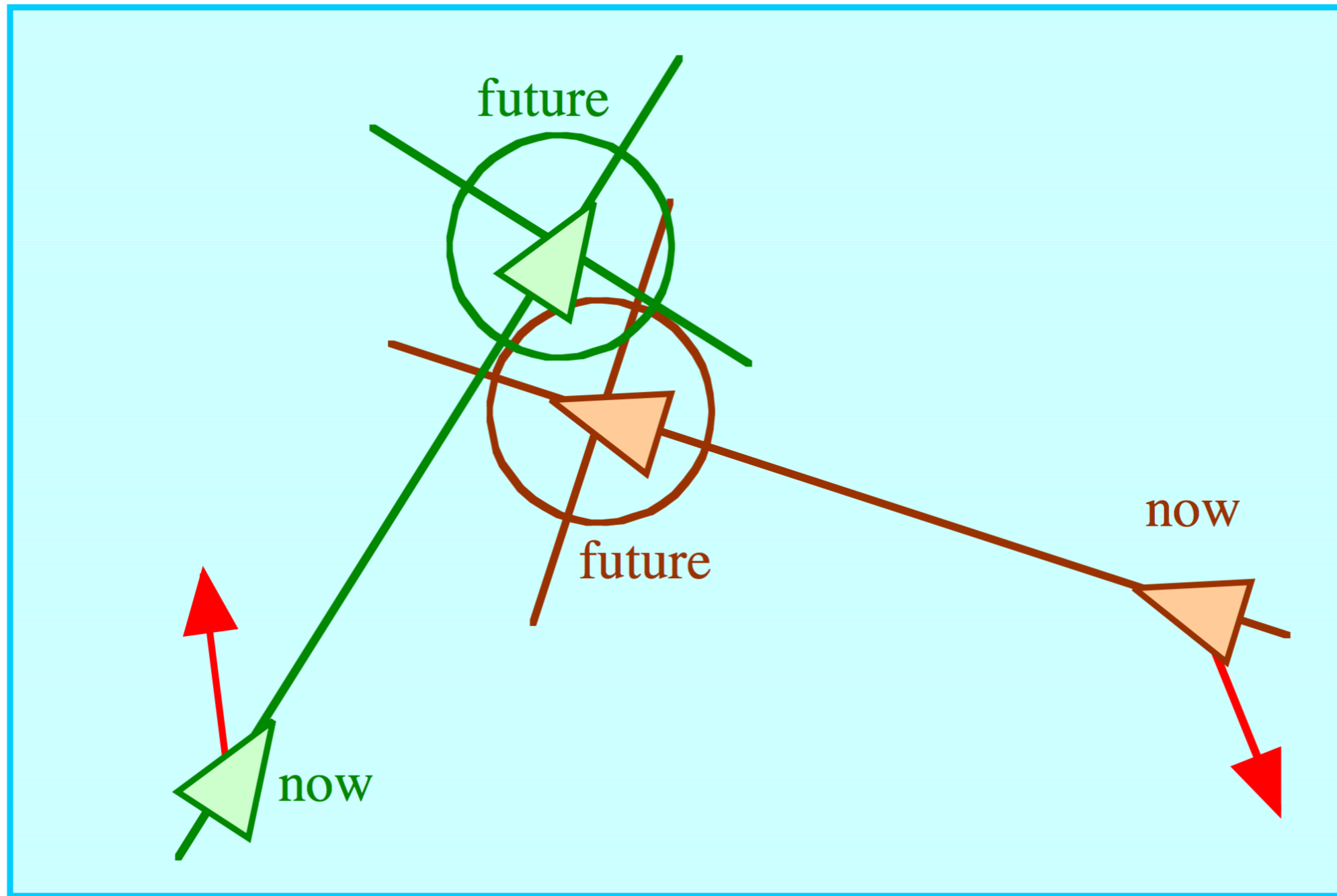
offset pursuit



arrival steering behavior



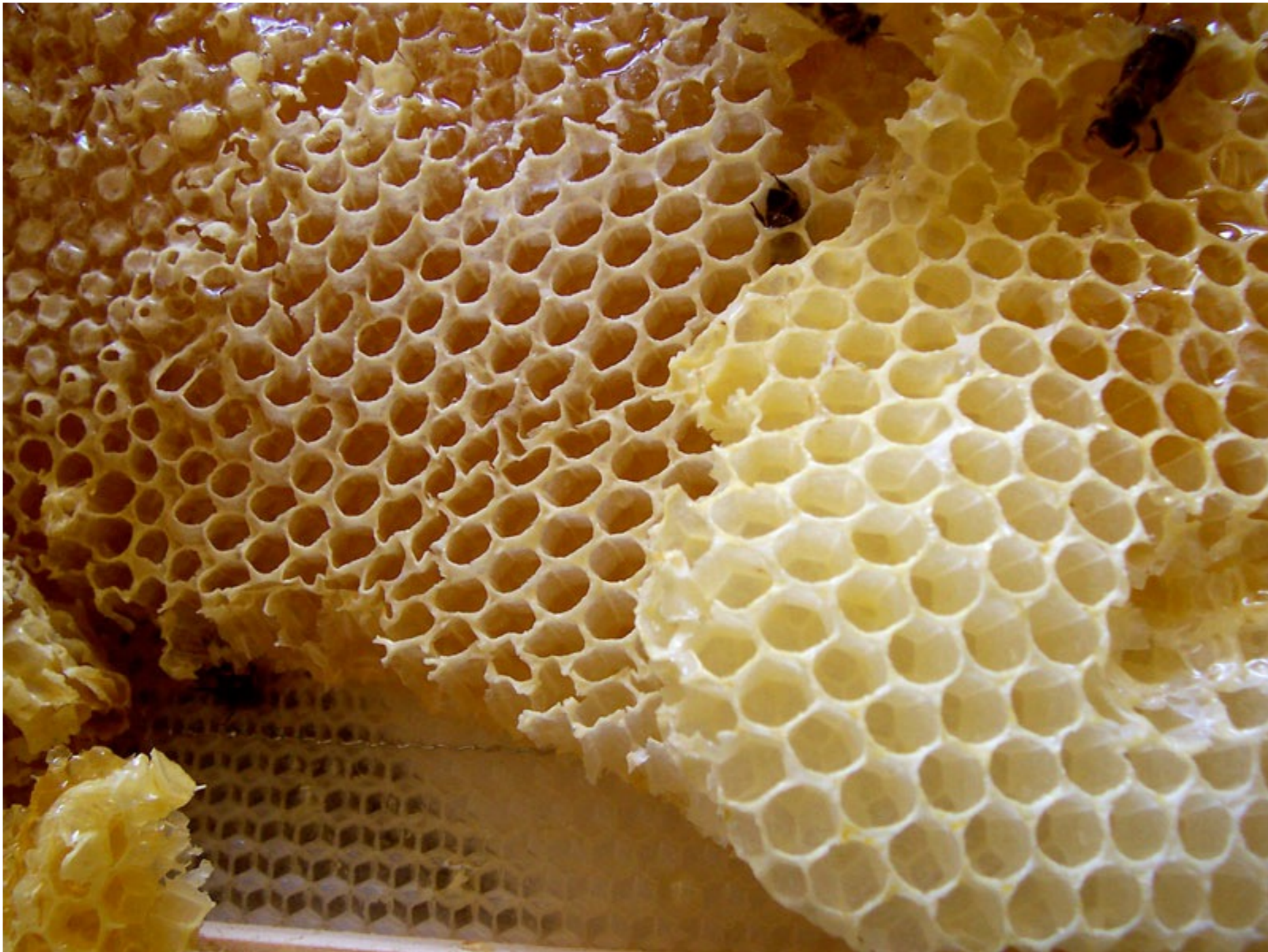
path following



unaligned collision avoidance

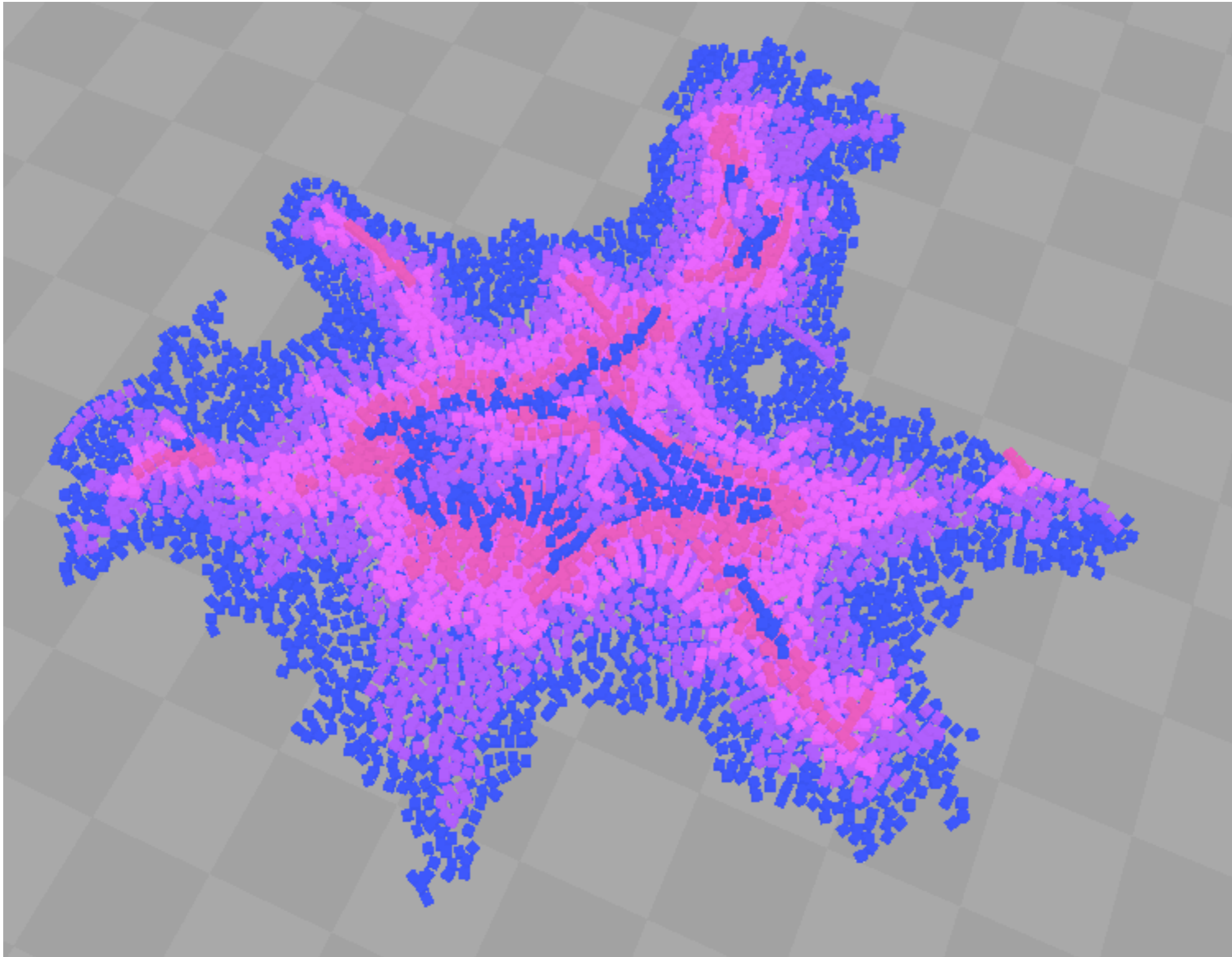
Stigmergy and collective construction

Collective construction: bees building honeycomb



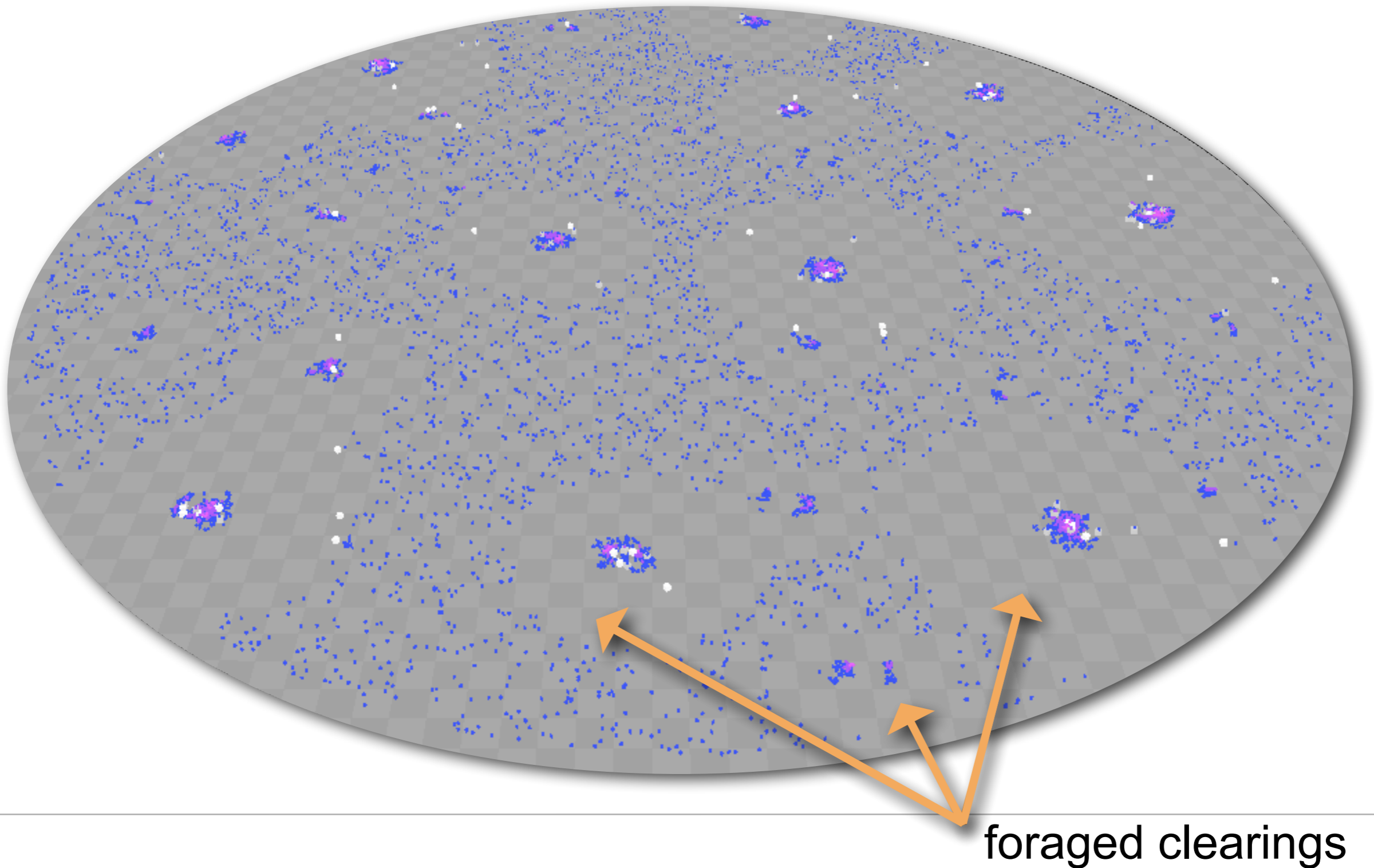
Collective construction: termite mound size





8000 bricks

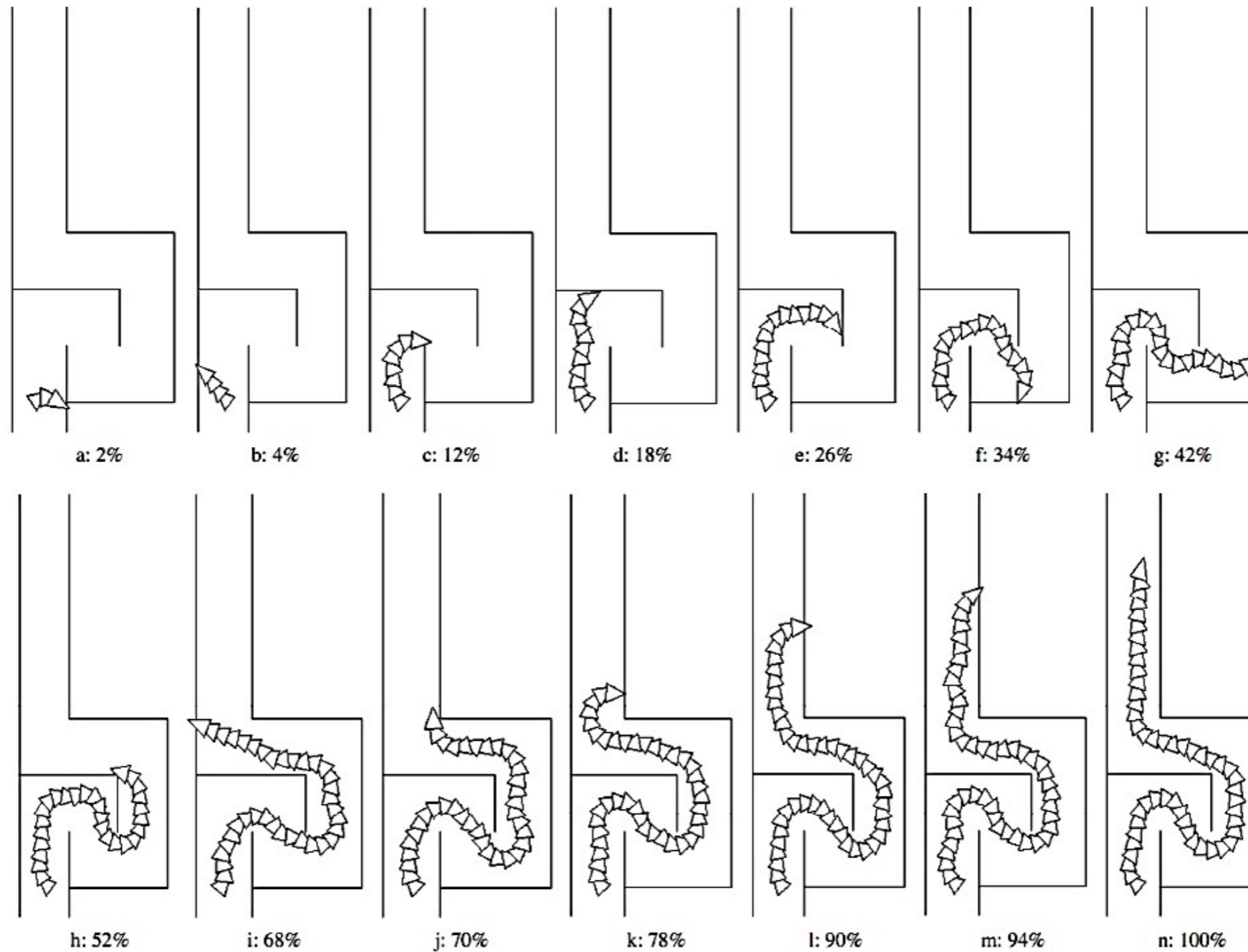
Stigmergy: emergent team construction





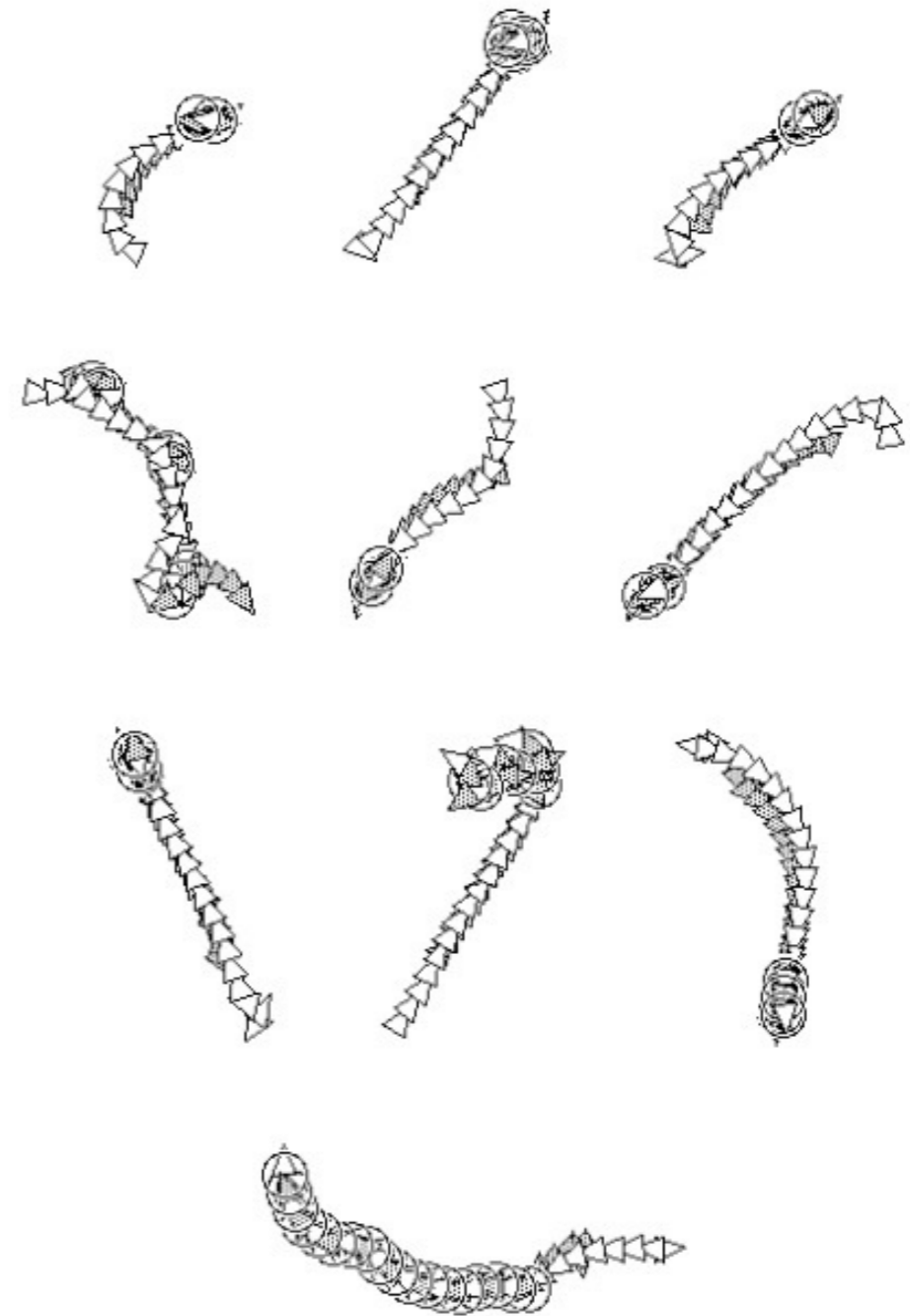
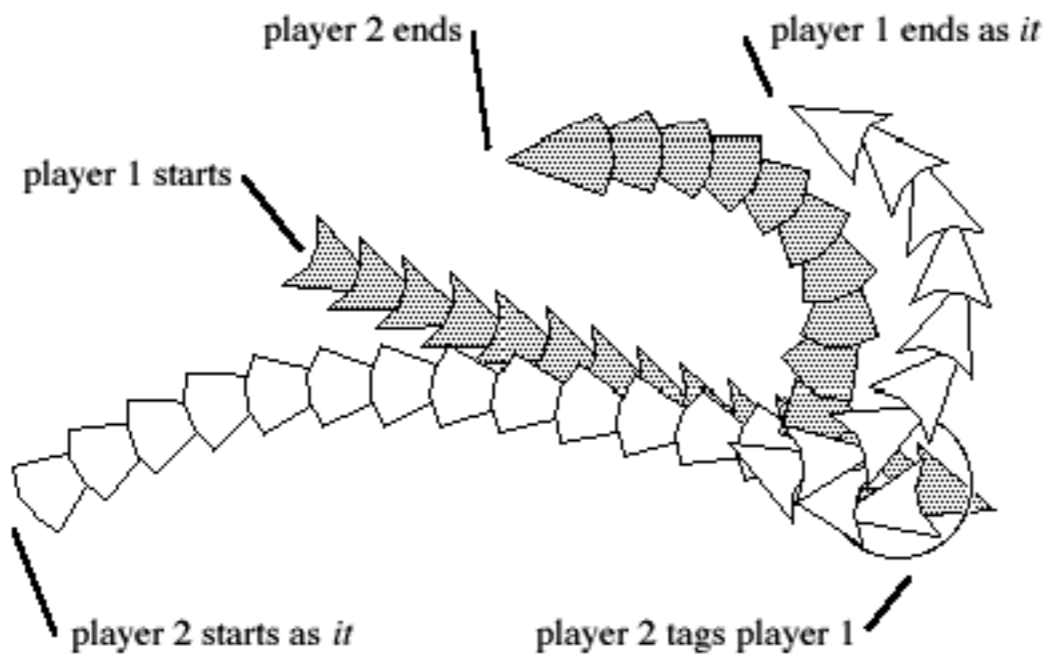
Evolutionary optimization of steering behaviors

Evolutionary Steering



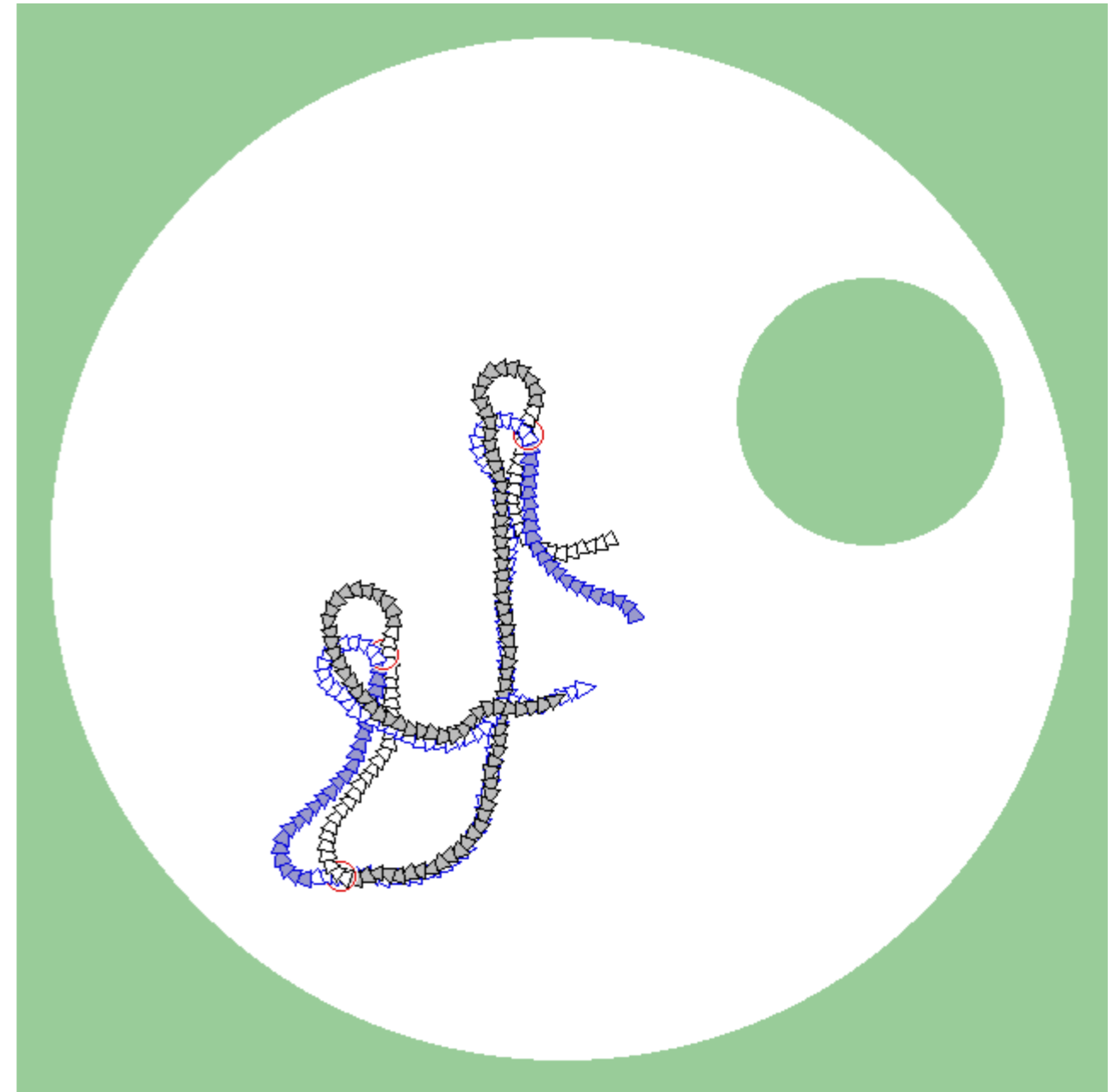
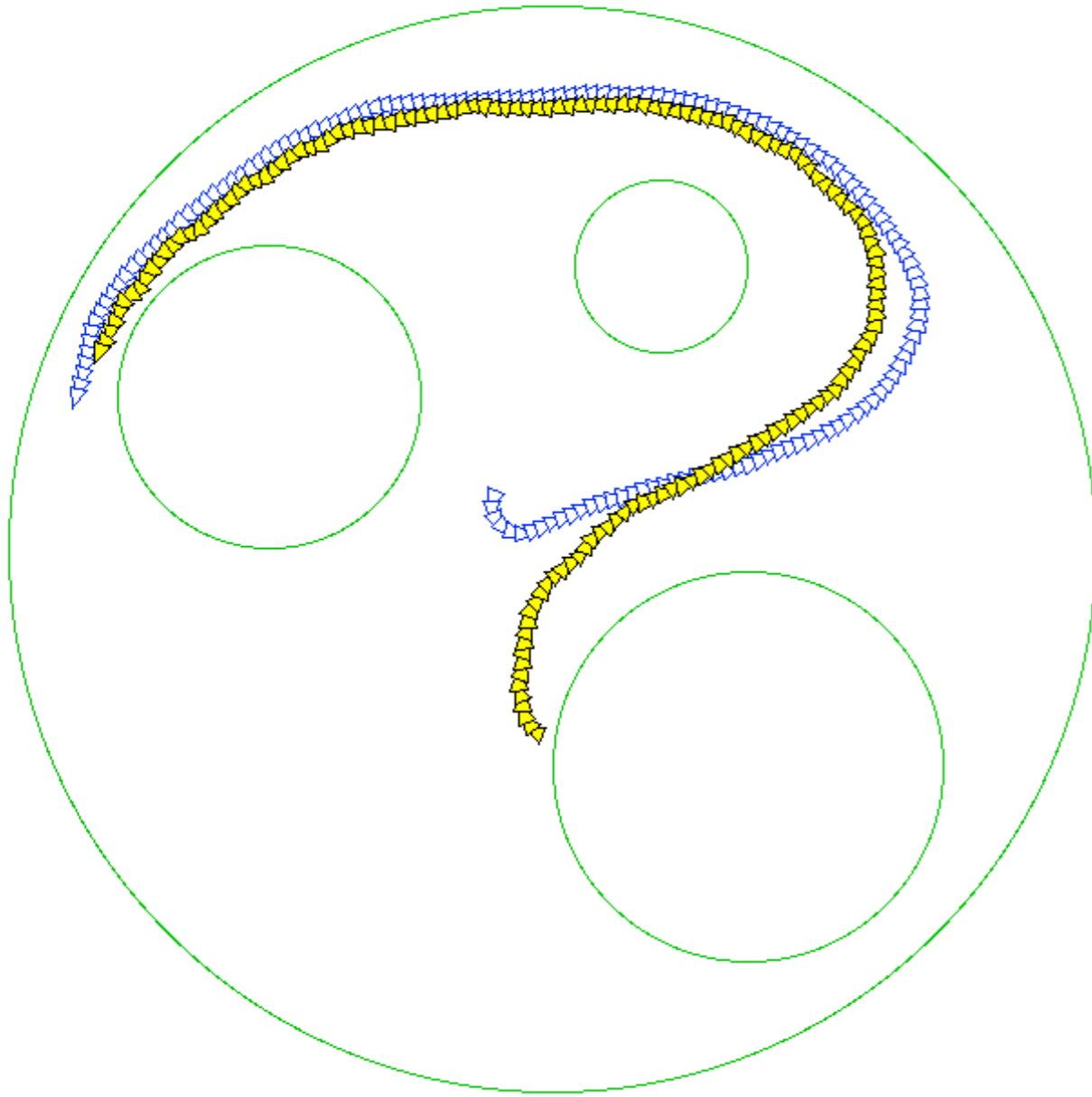
Evolution of Corridor Following Behavior in a Noisy World — SAB 1994

Evolutionary Steering



Competition, Coevolution and the Game of Tag — ALife 1994

Evolutionary Steering



subsequent work on “tag” with obstacles — unpublished

Steering behaviors on the web

In addition to your textbook, some other resources:

- 1999 paper, Java demos: <http://www.red3d.com/cwr/steer/>
(Google “steering behaviors”)
 - OpenSteer:
<http://opensteer.sourceforge.net/>
 - *Understanding Steering Behaviors* by Fernando Bevilacqua
<http://gamedev.tutsplus.com/author/fernando-bevilacqua/>
 - These slides:
http://www.red3d.com/cwr/temp/2013_Steering_Behaviors.pdf
-

these slides: http://www.red3d.com/cwr/presentations/2016_UCSC_Steering_Behaviors.pdf

Thank you!

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