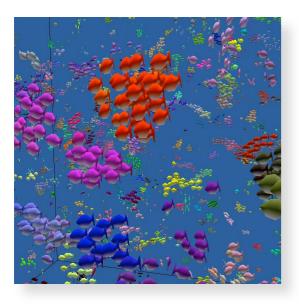


Steering Behaviors



Craig Reynolds

presented at: UCSC CMPS146 Game Al October 16, 2013

In this talk

history

versus

talk order

- History (mine and steering behaviors)
- Flocking boids (self-organization, emergence)
- Generalizing steering behaviors
- OpenSteer (open source library)
- Other collective behavior models (stigmergy)
- Learning/optimization applied to steering behaviors

History

- Childhood interest in bird flocks and "model worlds"
- College work on multi-agent simulations in 3d worlds
- SIGGRAPH 1986: first boids motion tests
- SIGGRAPH 1987: boids paper, Breaking the Ice
- GDC 1999: paper on generalized steering behaviors
- GDC 2000: real time interactive boids
- 2003 OpenSteer (C++ lib, ports to other languages)
- 2006: high performance multicore/GPU versions

What are steering behaviors?

- Help autonomous characters navigate their world
- Get from here to there, without bumping into things
- Important in modeling embodied multi-agent systems
- Simulation model of human crowds and animal groups
- Applications in games, VR, and films (crowd scenes)

Steering behaviors: assumptions

- Position and orientation have continuous values
- Speed high enough that momentum matters
- Each agent runs their own behaviors
- Behaviors based on perception of local environment
- Environment is world geometry plus nearby agents
- Typically reactive behavior, not long term planning

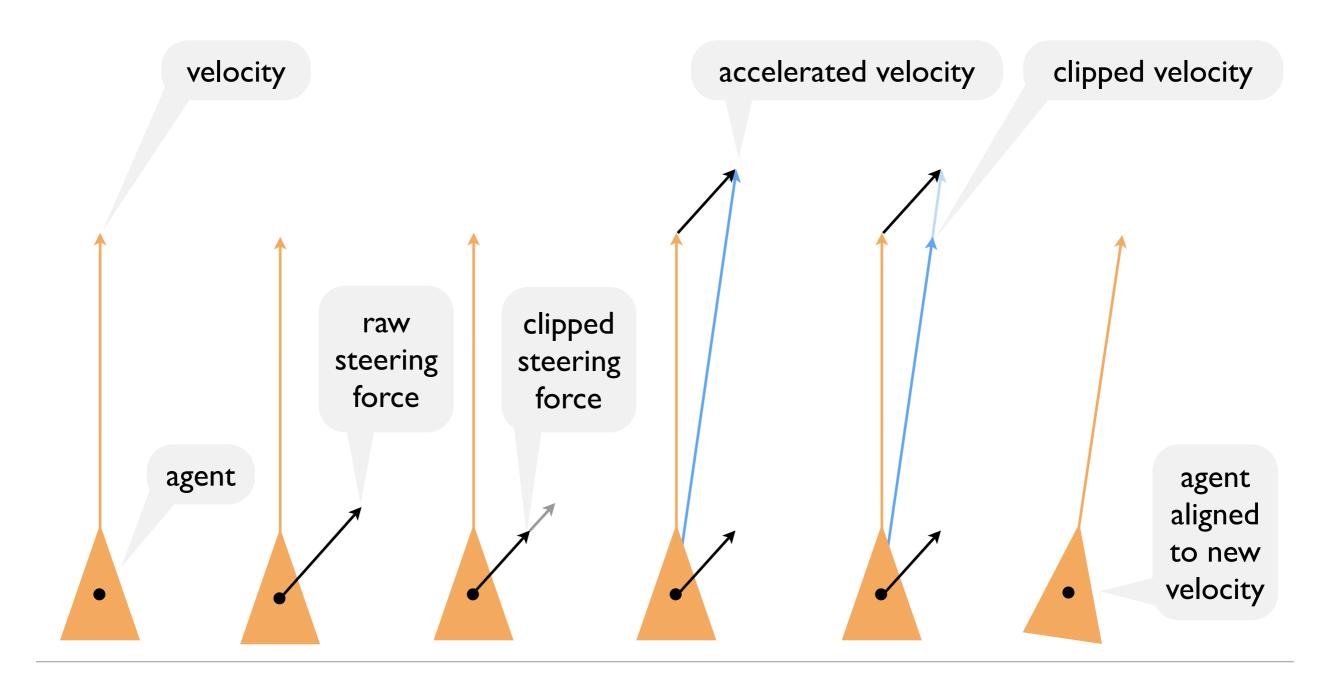
Typical steering behaviors

- seek / flee
- pursue / evade
- wander
- arrival
- avoid obstacle
- containment
- path following

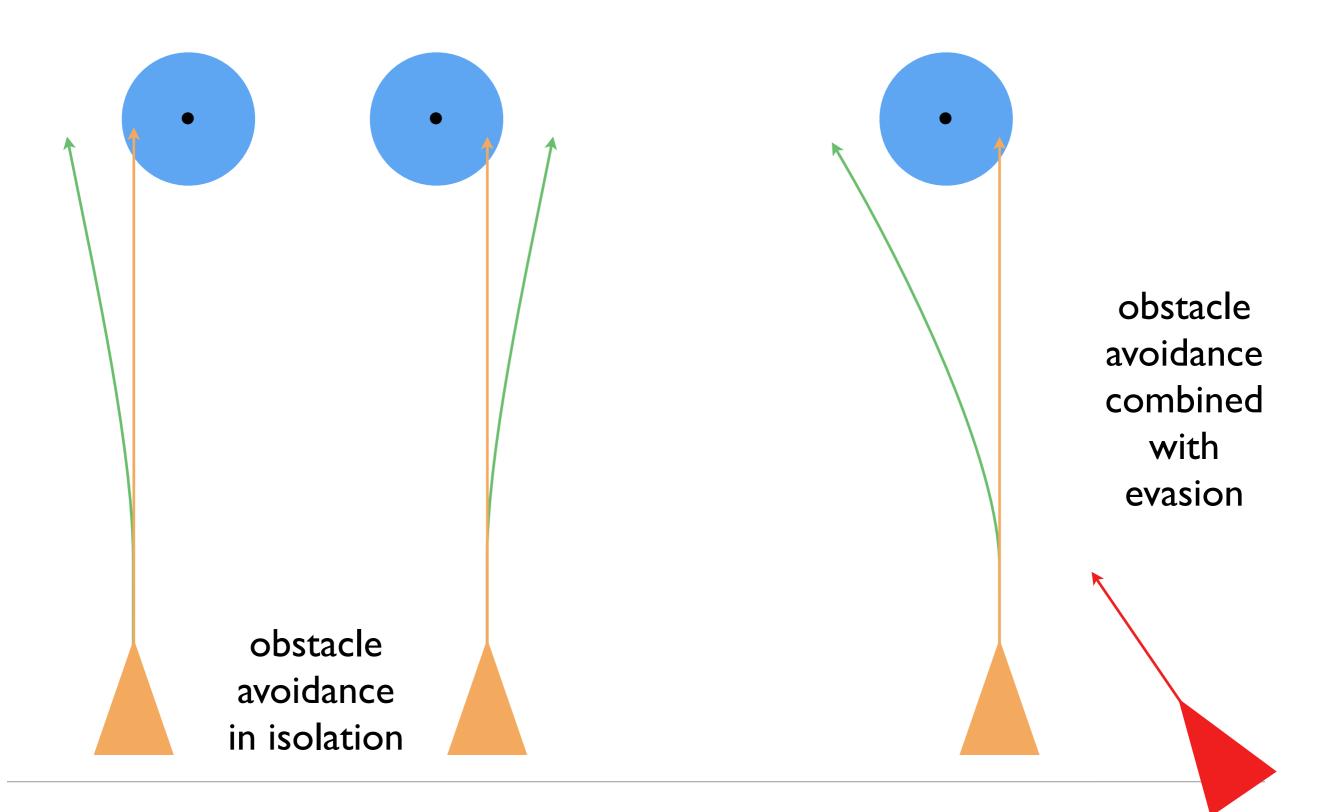
- wall following
- flow field following
- flocking
 - separation
 - alignment
 - cohesion

Steering Behaviors

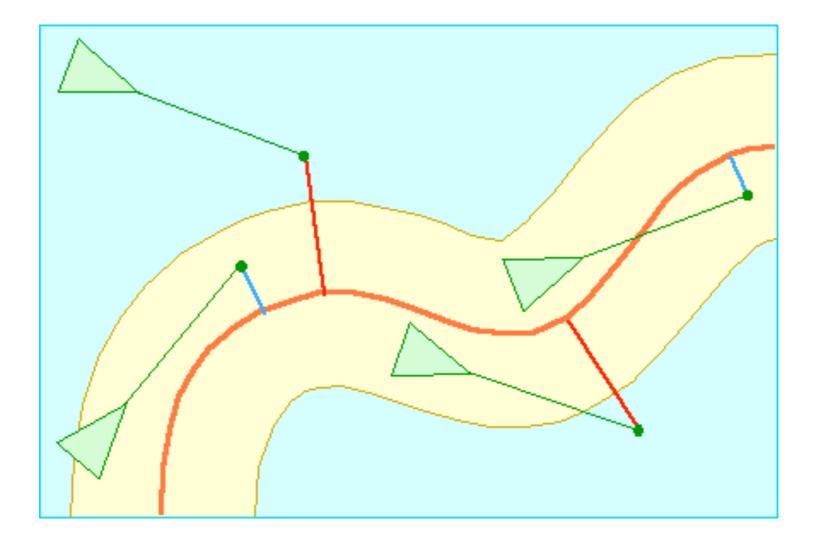
applying steering forces to velocity-aligned point mass "vehicles"



Combining steering behaviors

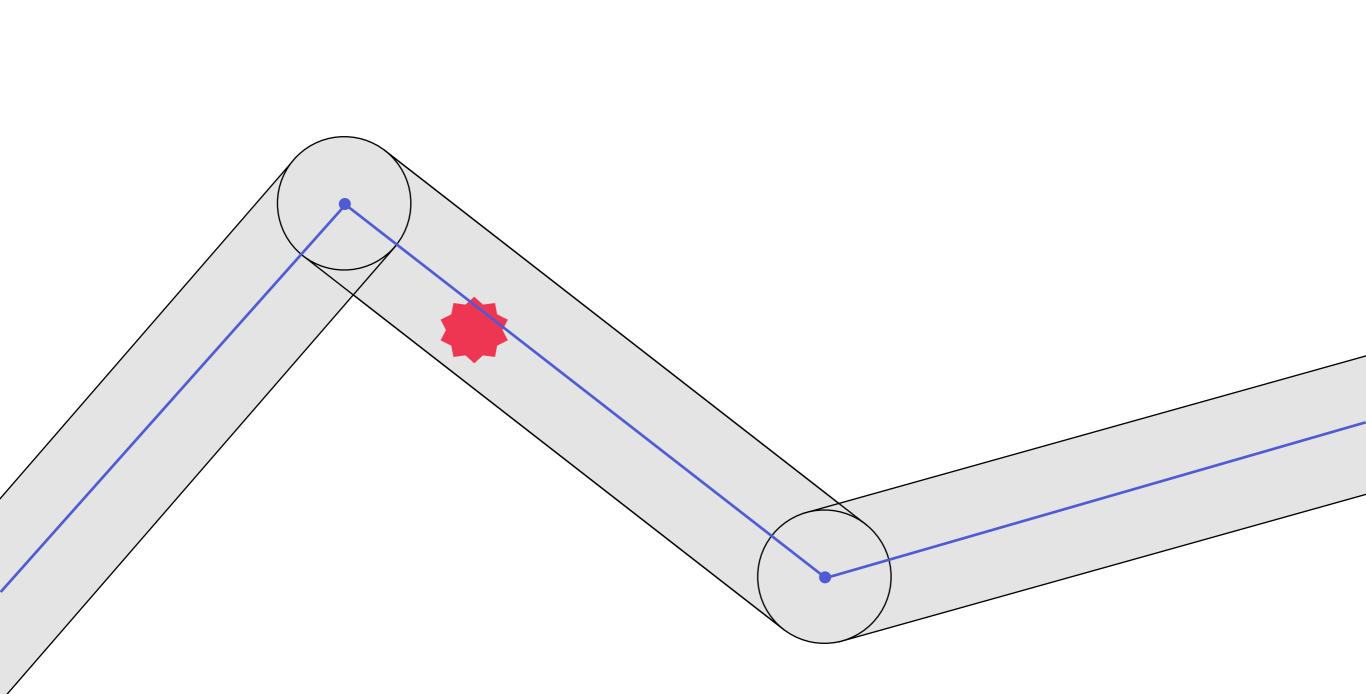


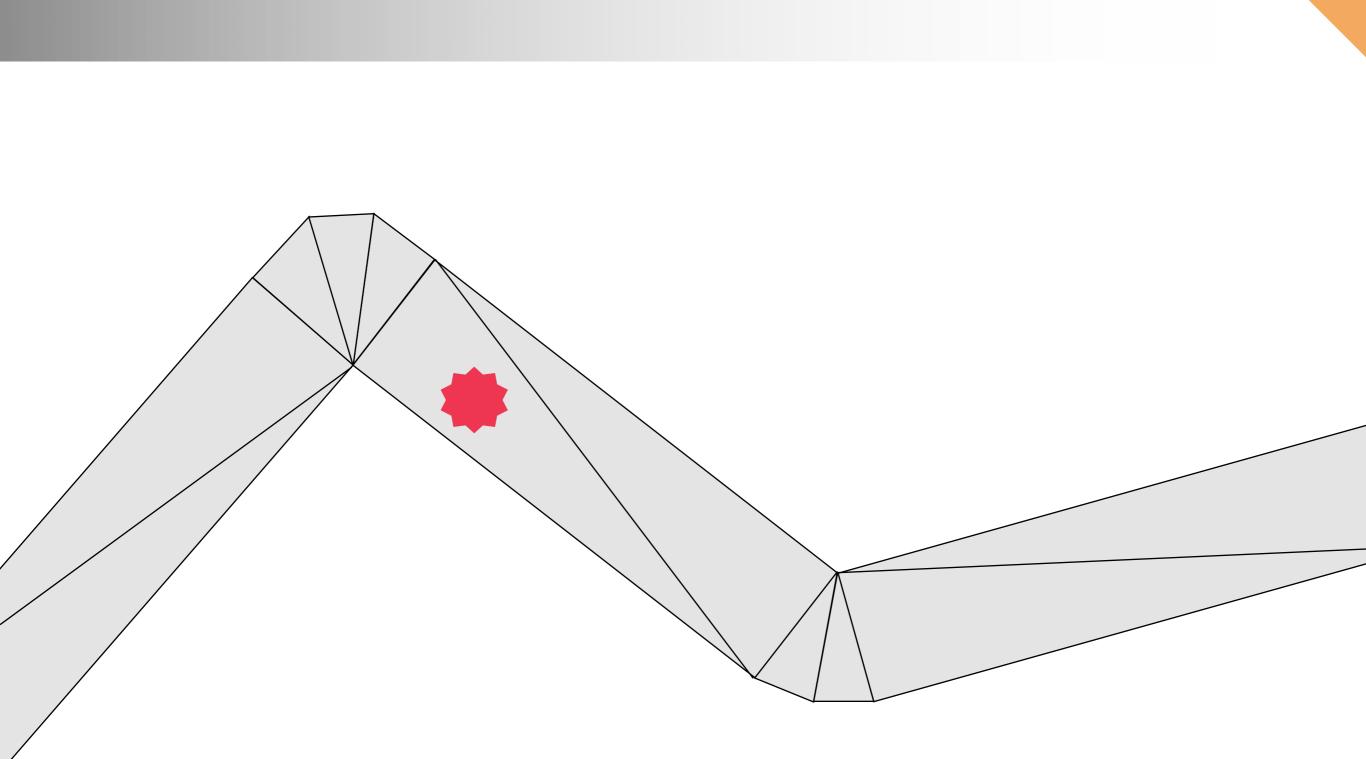
Steering behavior example: path following



composed steering behaviors: follow path and avoid obstacle

sphere swept along polyline

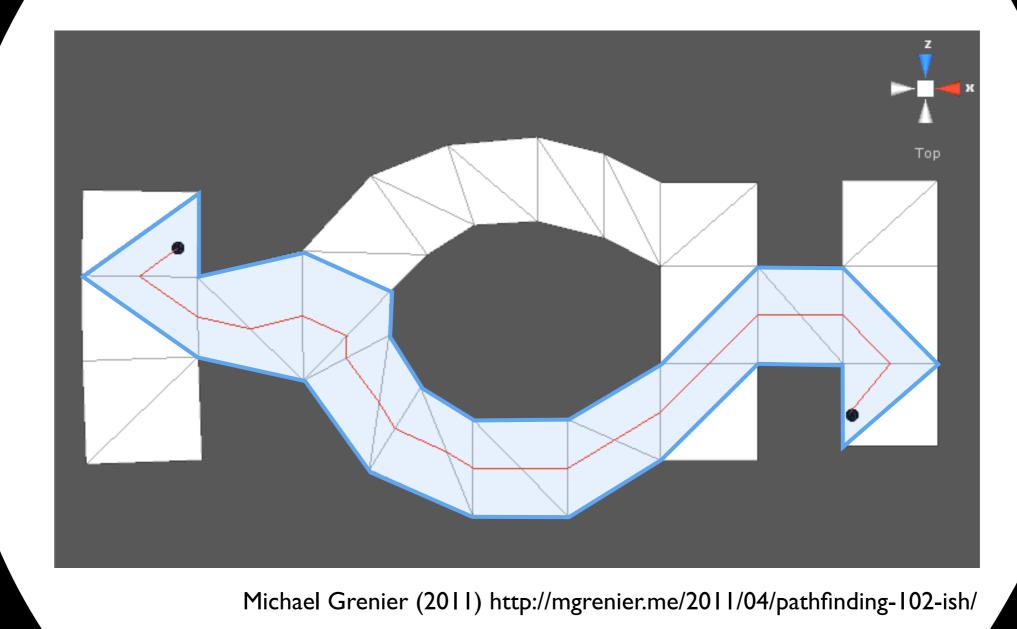




navigation mesh

navmesh: a parenthetical aside Тор Michael Grenier (2011) http://mgrenier.me/2011/04/pathfinding-102-ish/

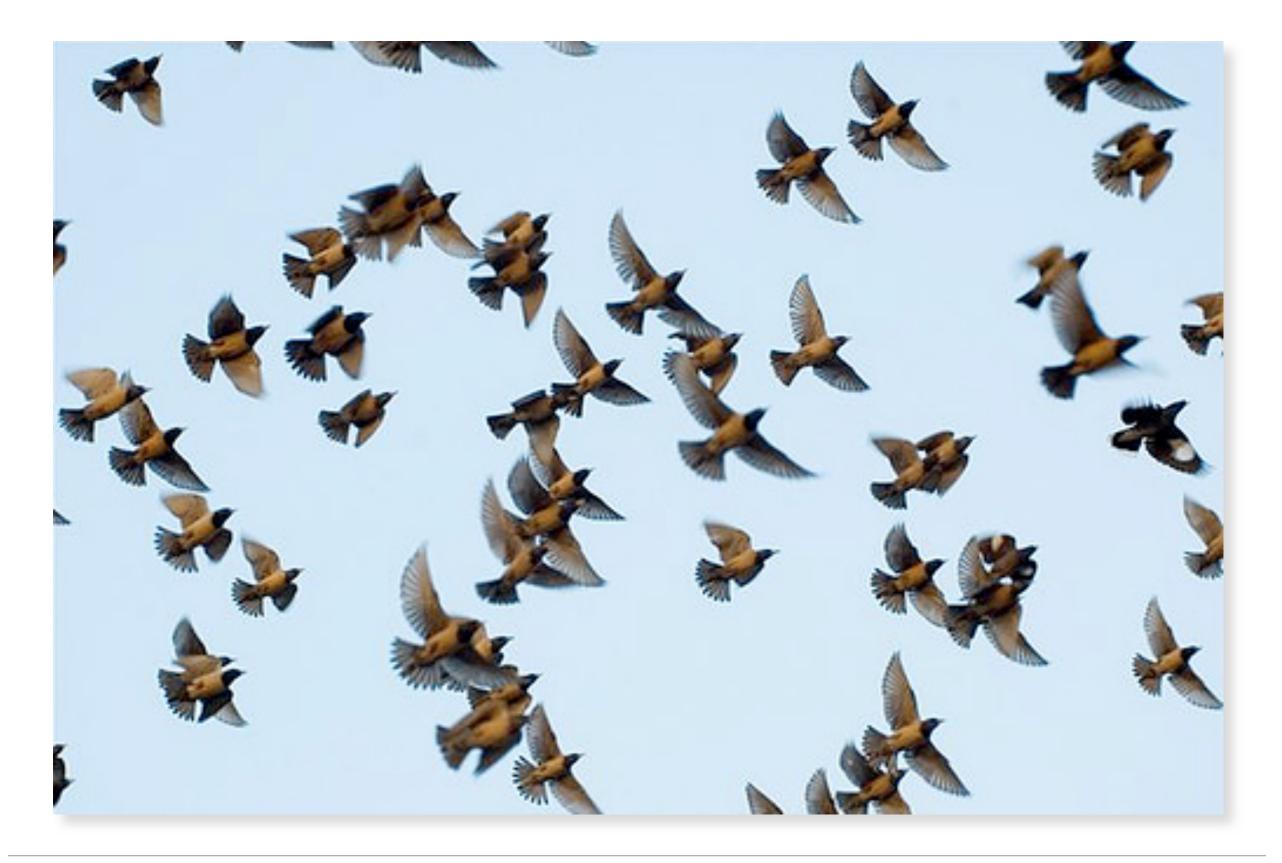
navmesh: a parenthetical aside



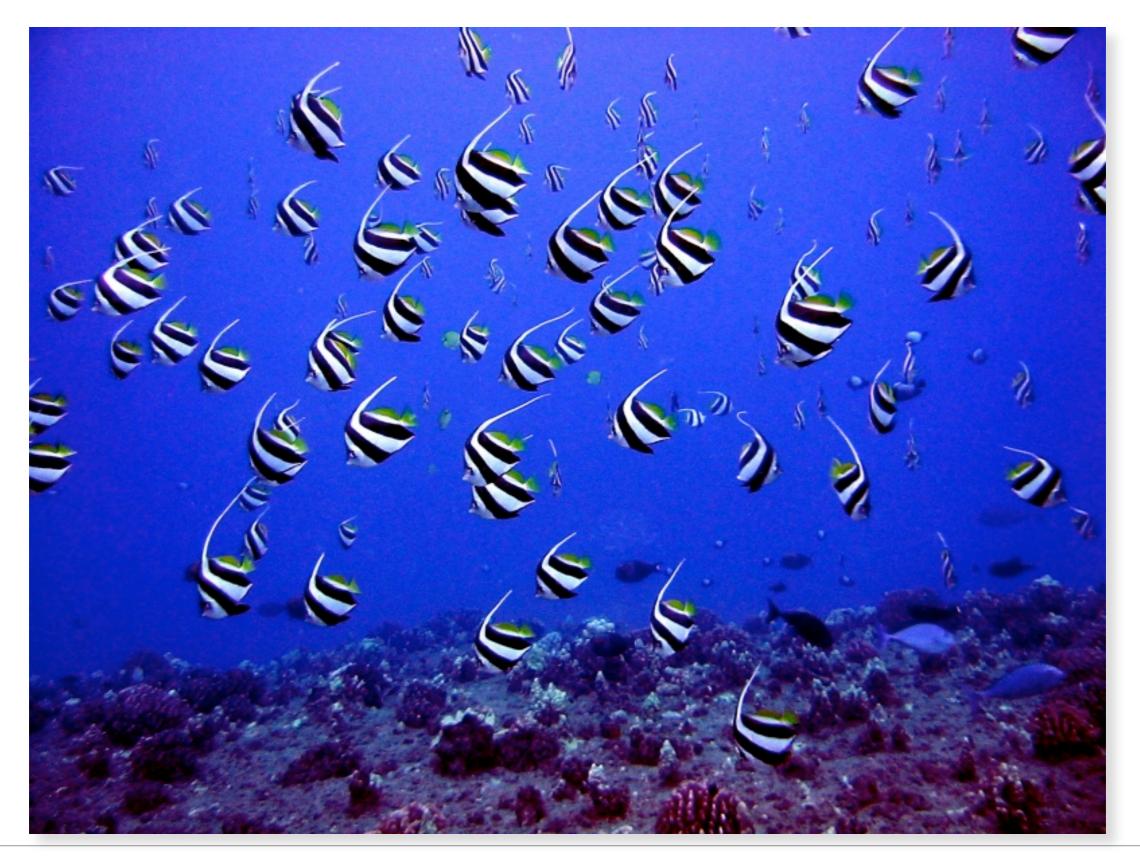
Steering demos in Java





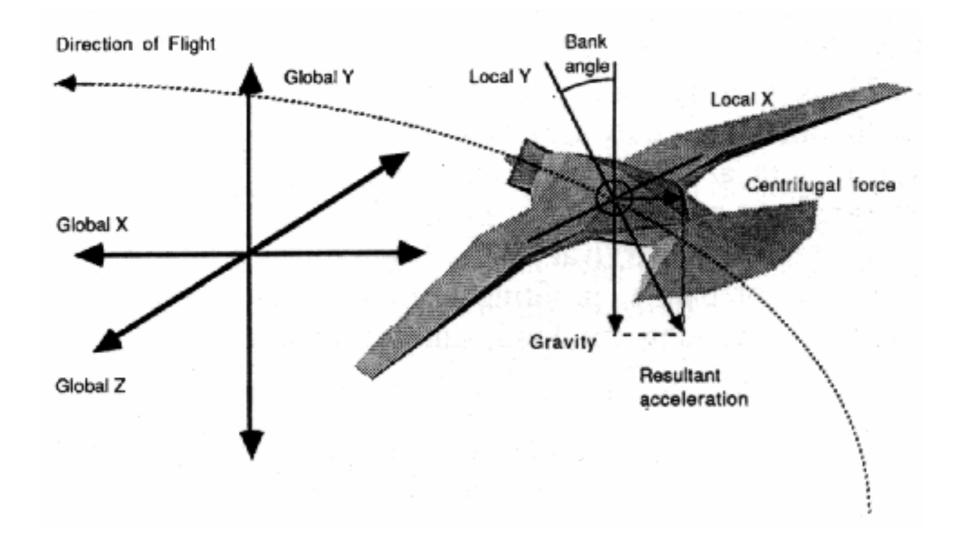






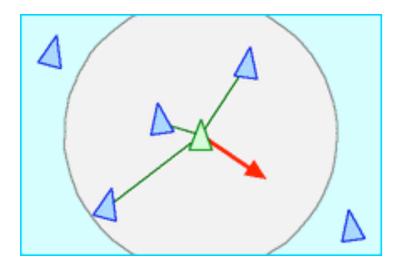
Self-organization

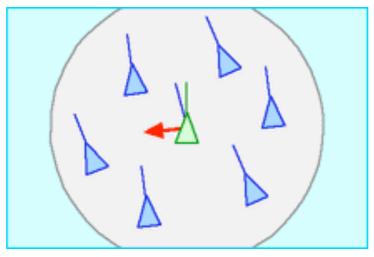
- many autonomous agents ("multi-agent simulation")
- Iocal interaction between neighboring agents
- emergence of global behavior or structure

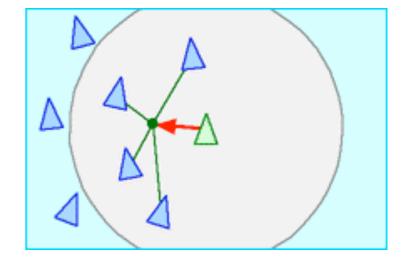


boid's local coordinate system and banking

Three component steering behaviors of flocking:



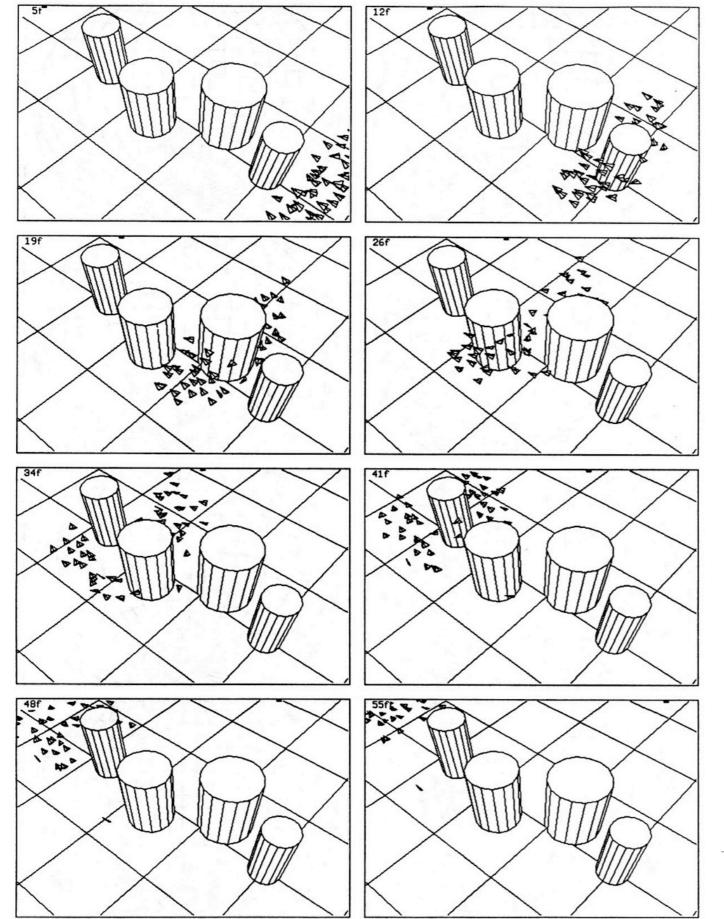




Separation

Alignment

Cohesion



Early boids motion test:

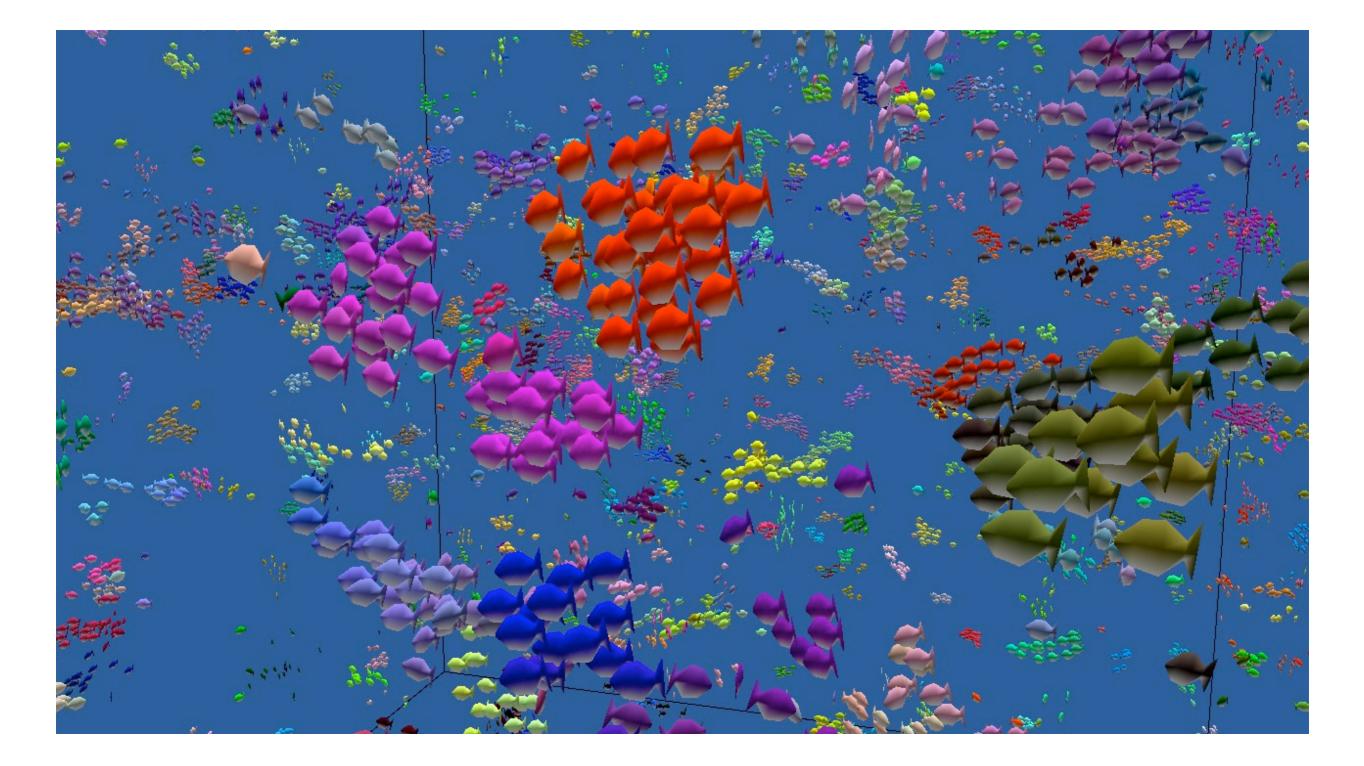
- flocking
 - separation
 - alignment
 - cohesion
- seek
- obstacle avoidance

1986 screen grabs from Symbolics Lisp Machine



(Stanley and Stella in) Breaking the Ice 1987



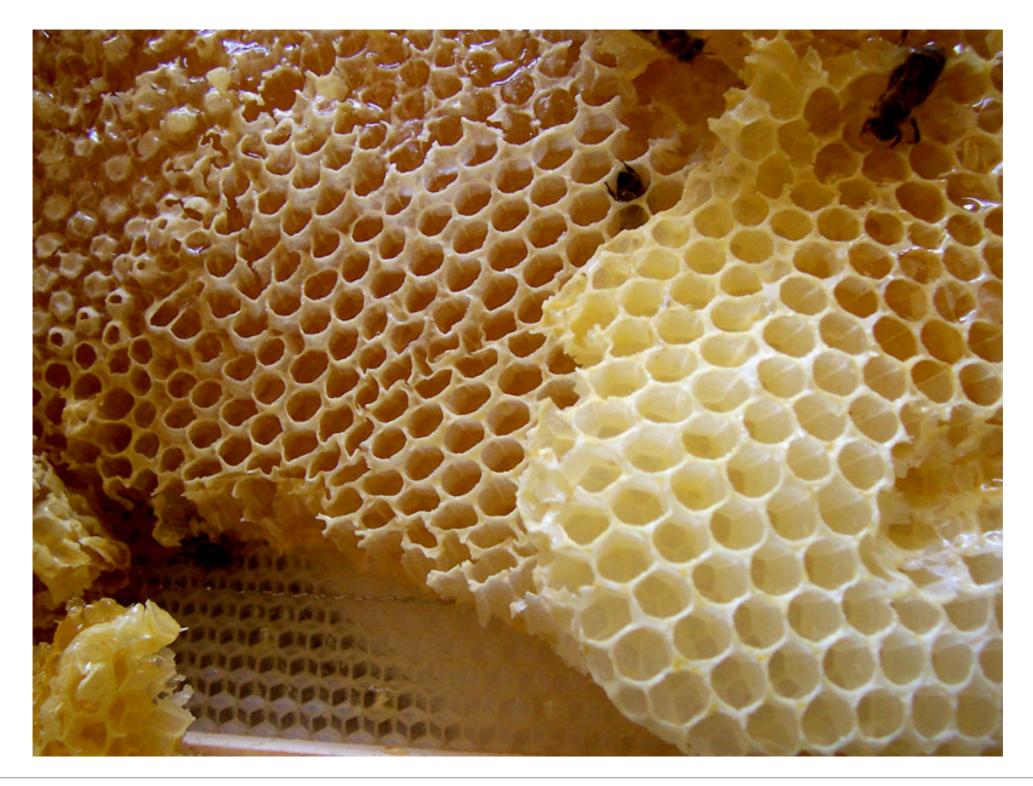


Real time boids on PS3 — about 10,000 at 60Hz — PSCrowd, 2006

video: | 2k fish

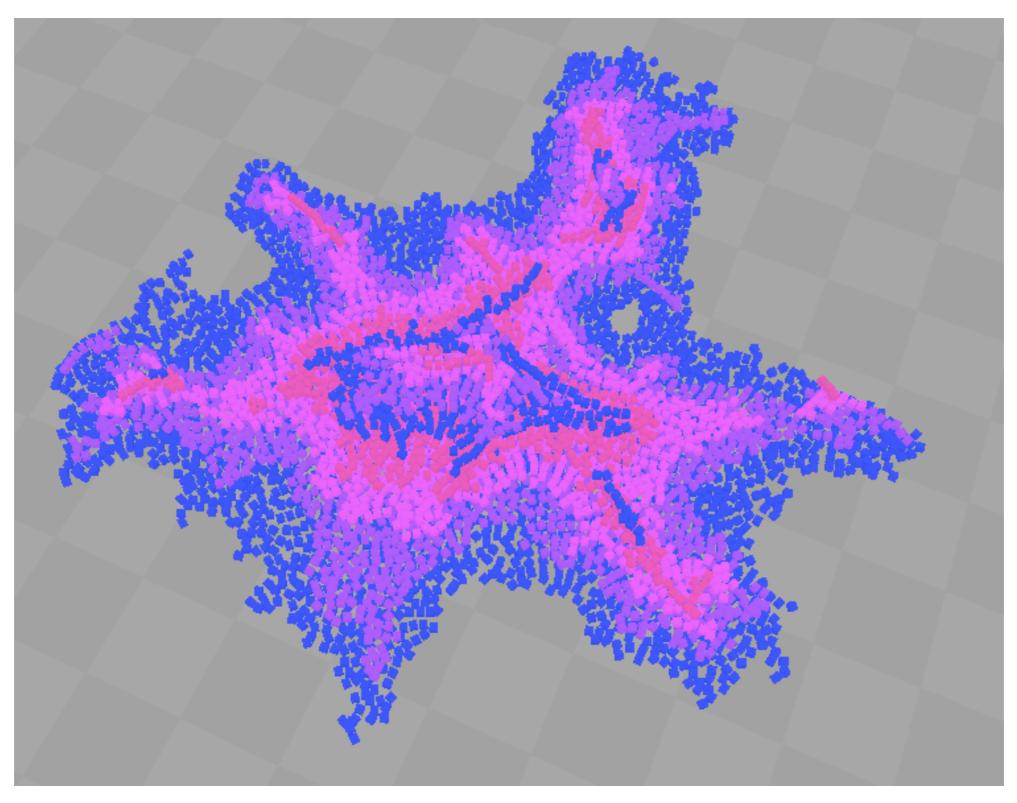
Stigmergy and collective construction

Collective construction: bees building honeycomb



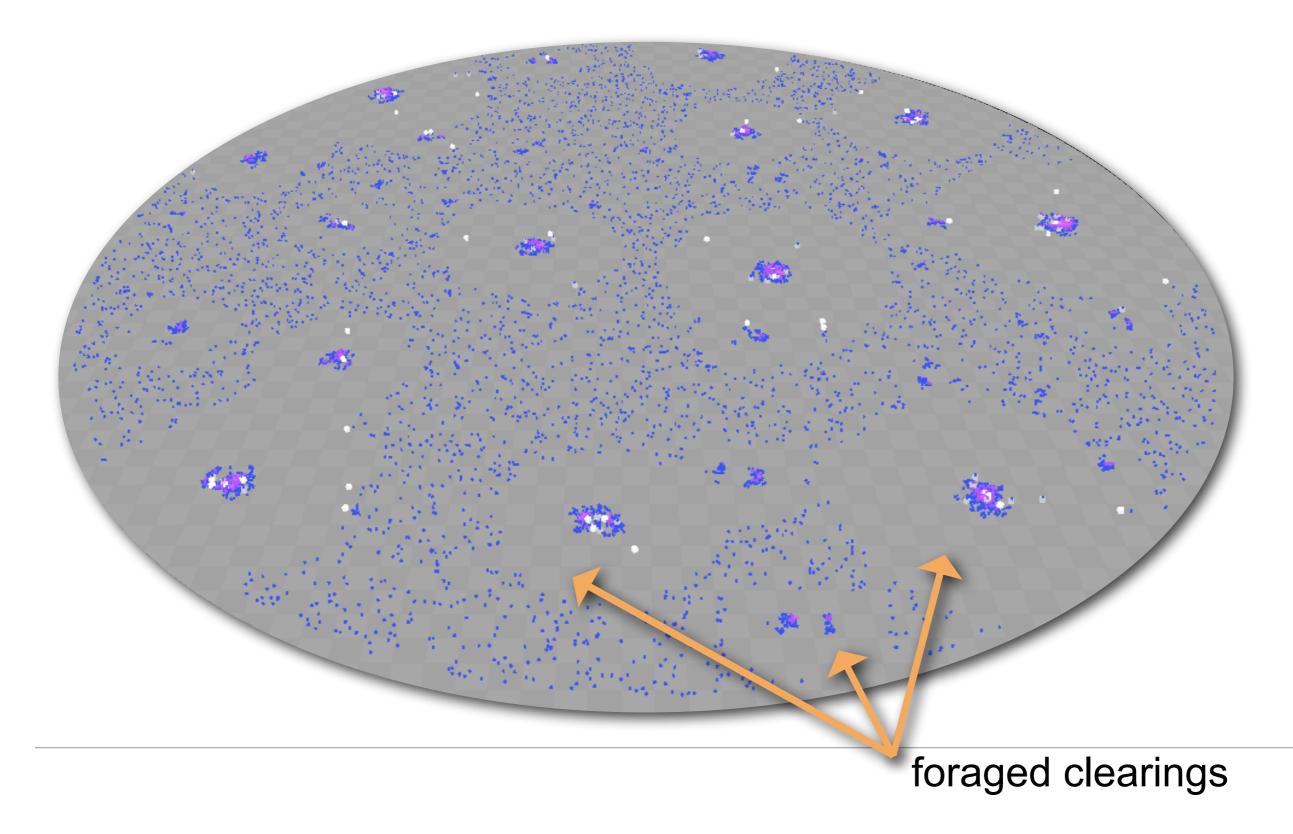
Collective construction: termite mound size





8000 bricks

Stigmergy: emergent team construction

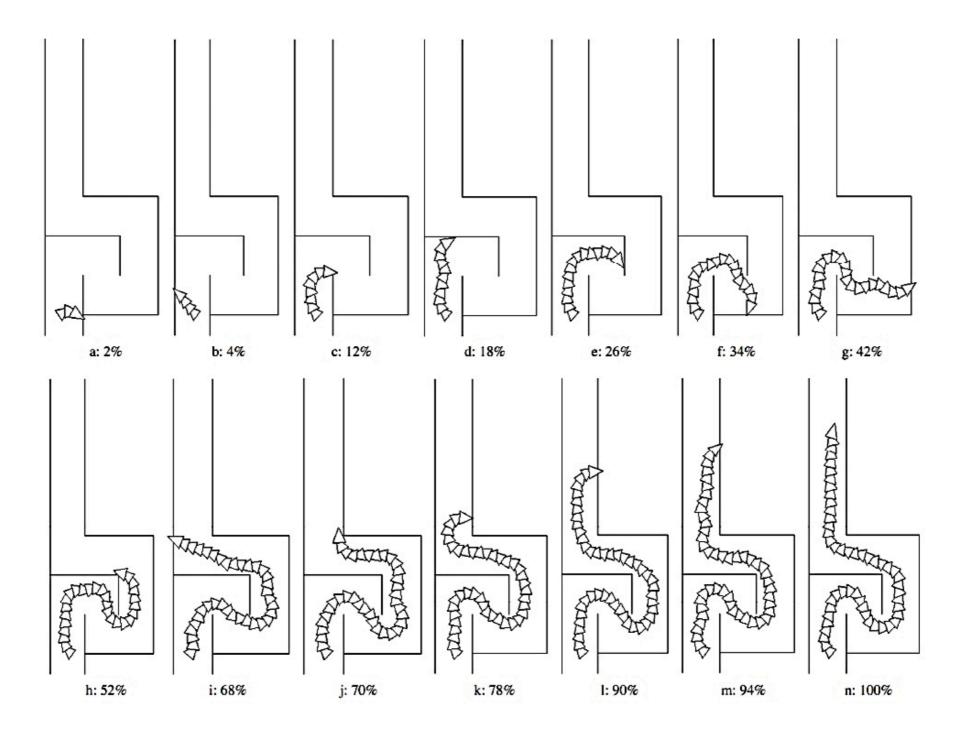




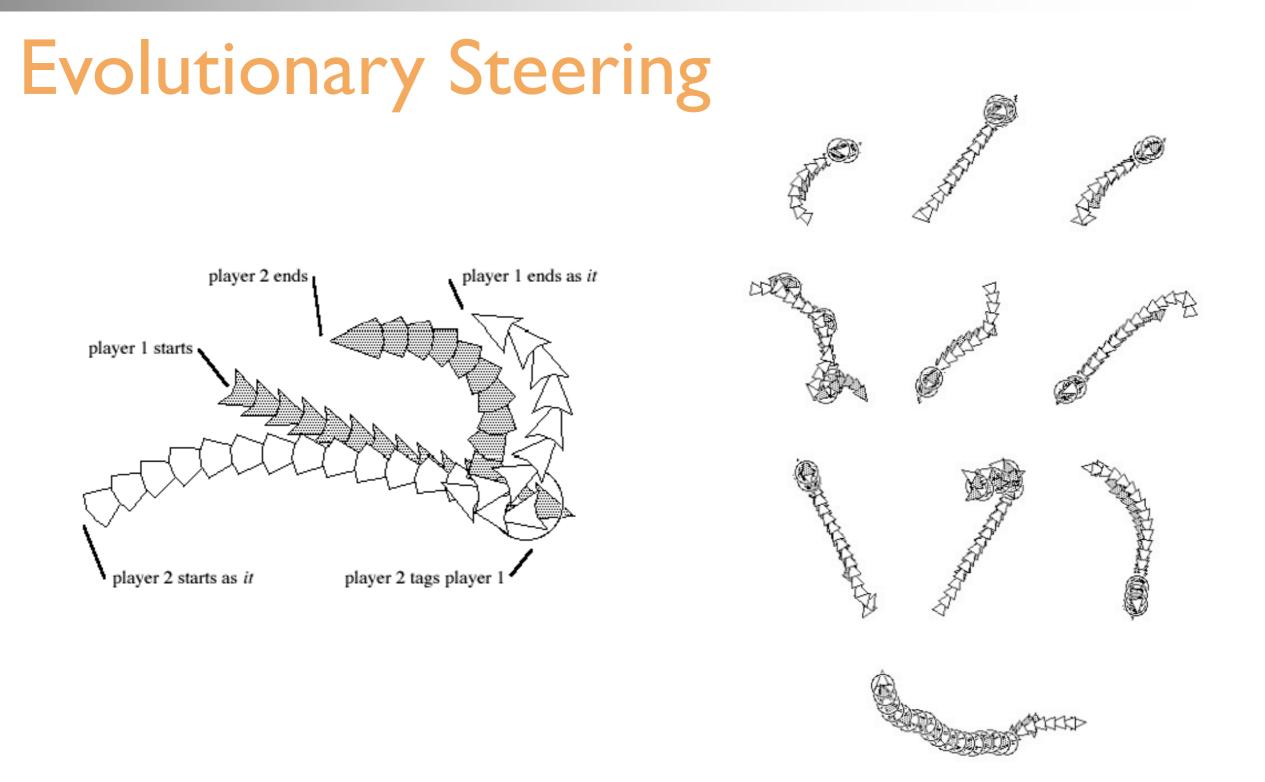


Evolutionary optimization of steering behaviors

Evolutionary Steering

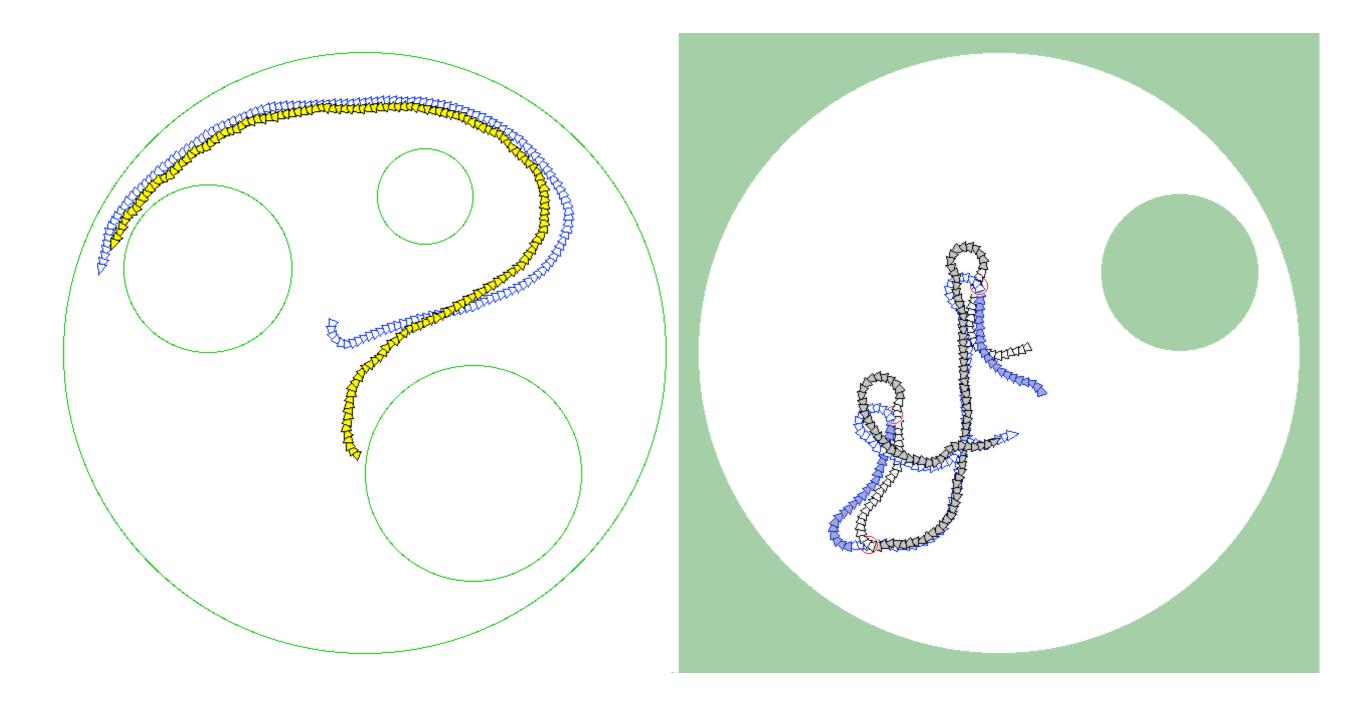


Evolution of Corridor Following Behavior in a Noisy World — SAB 1994



Competition, Coevolution and the Game of Tag — ALife 1994

Evolutionary Steering



subsequent work on "tag" with obstacles — unpublished

Steering behaviors on the web

In addition to your textbook, some other resources:

- I999 paper, Java demos, etc.: http://www.red3d.com/cwr/steer/ (Google "steering behaviors")
- OpenSteer: http://opensteer.sourceforge.net/
- Understanding Steering Behaviors by Fernando Bevilacqua http://gamedev.tutsplus.com/author/fernando-bevilacqua/

These slides:

http://www.red3d.com/cwr/temp/2013_Steering_Behaviors.pdf

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Thank you!

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